

Urban Forest Extraction

Use of Remote Sensing Datasets to
Quantify Urban Forest Coverage in
Mixed Land Use Areas

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Study Area



Morgan Hill, CA



Project Objective

- Collaborate with City of Morgan Hill on using GIS data to identify the tree canopy in the Morgan Hill Region.
- Develop an automated methodology using available data sets and tools.
- Ensure developed methods adhere to professional standards and return valid results.



Data Sets & Coverage

2006 LIDAR Grid

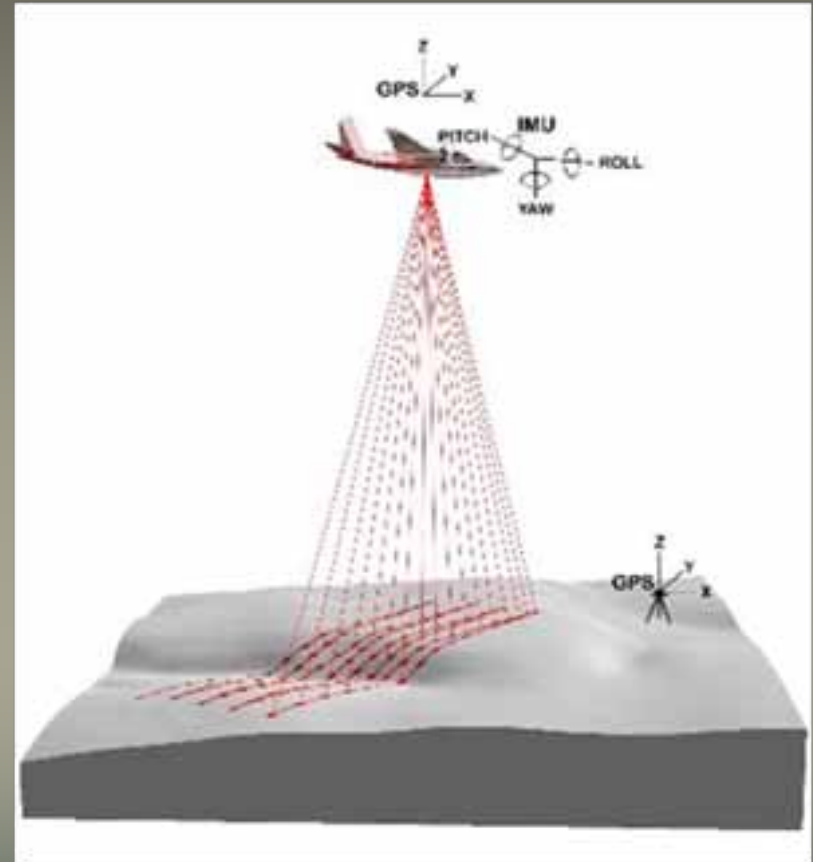


2006 Ortho-Photography Grid



LIDAR Definition

- **LIDAR** (*Light Detection and Ranging*) is an optical remote sensing technology that measures properties of scattered light to find range and/or other information of a distant target.



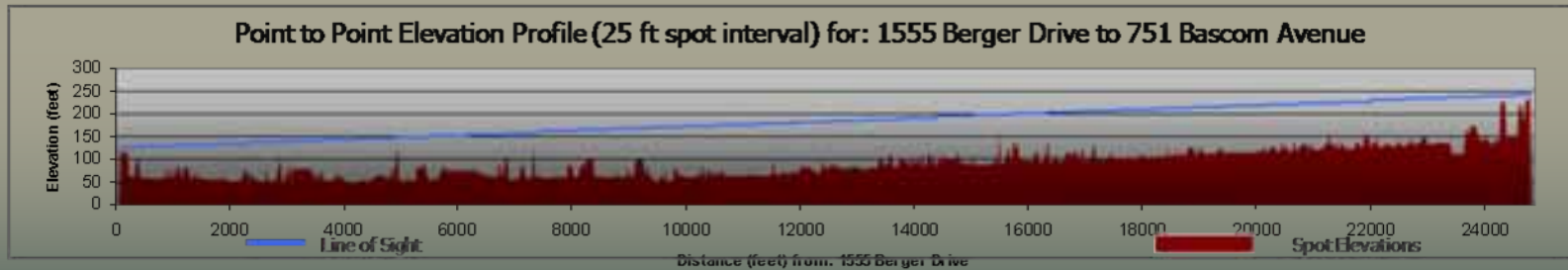
2006 Lidar Data Set – Potential

Building Footprint Extraction

3-D Modeling



Line of Sight Analysis



2006 Ortho-Photo Data Set – Potential



Available Tools



ArcGIS Spatial Analyst
Advanced Raster GIS Spatial Analysis

OVERWATCH
TEXTRON Systems

Visual Learning Systems

sales@vls-inc.com
1-866-YOUR-VLS

LiDAR Analyst

Feature Analyst



Preliminary Results

- Utilizing Lidar data set and Lidar Analyst.
- Excellent point identification.
- Poor forest and extent identification.
- Estimated coverage - area: 160,000 sq. feet (5.7%).



Preliminary Results

- Utilizing Ortho data set and Feature Analyst.
- Excellent forest coverage
- Poor discrimination of shrubs, grasses and trees.
- Estimated coverage - area 424,000 sq. feet (14.7%).



Synthesized Approach

- Exploit the horizontal dimension using Feature Analyst and Ortho-Imagery.
- Exploit the vertical dimension using Lidar Analyst and Lidar data.
- Combine these using Spatial Analyst from ESRI.

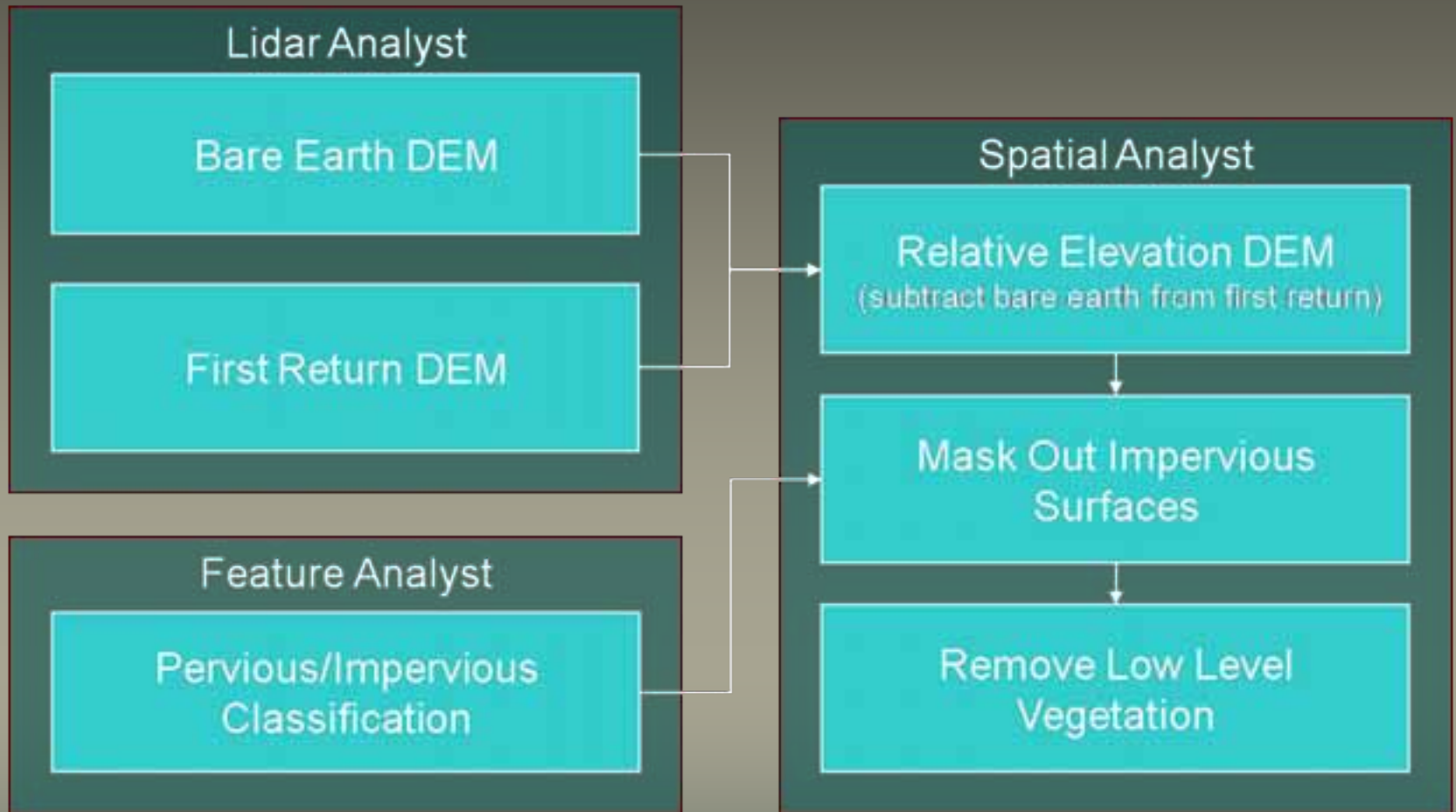


Acknowledgements

- Robert Colley – GIS Manager County of Santa Clara, “There must be a way to combine these data sets together to get an accurate result.”
- “Integrating LIDAR data and multi-spectral imagery for enhanced classification of rangeland vegetation: A meta analysis”, Edward W. Bork, Jason G. Su (2006) University of Alberta, University of British Columbia.



Synthesized Approach - Overview



First Return DEM

- Derived from Lidar Analyst.
- Includes first Lidar point elevation value.
- Lidar Tile Statistics:

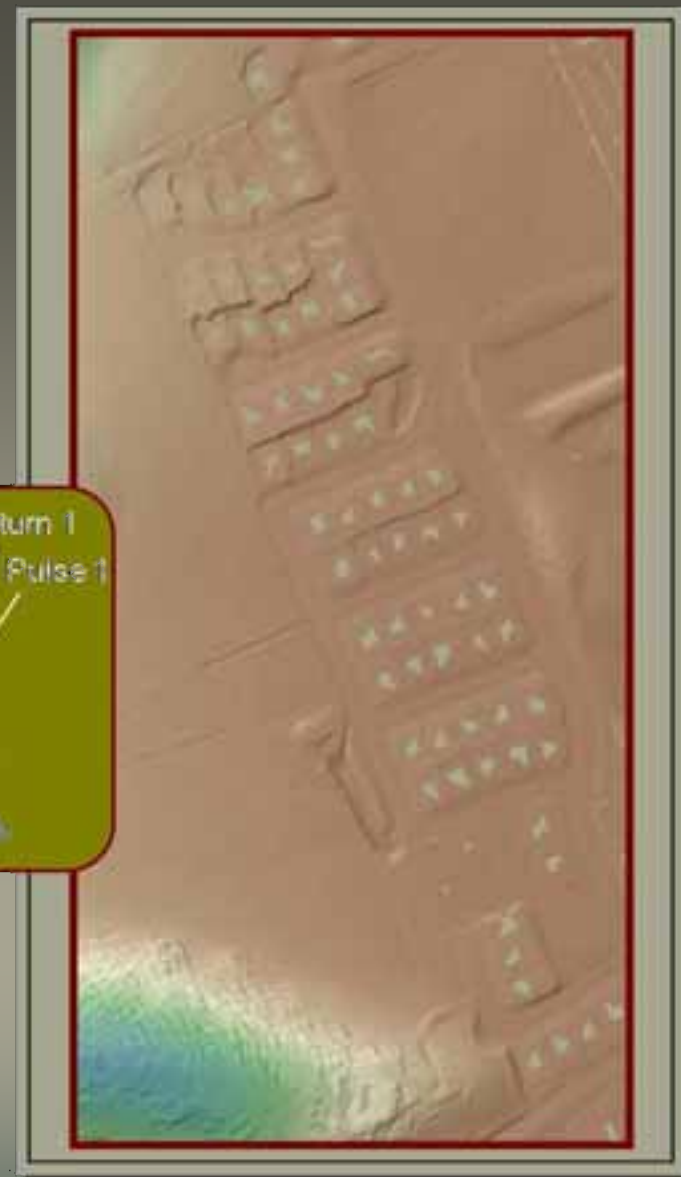
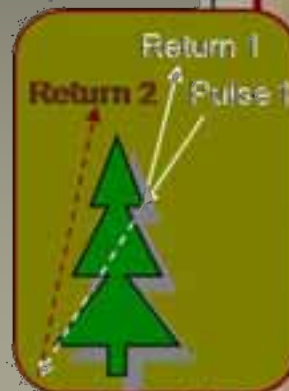
| # of returns per pulse | Return Number | | | | | |
|------------------------|---------------|--------|-----|---|---|---------|
| | 1 | 2 | 3 | 4 | 5 | Total |
| 1 | 445,681 | - | - | - | - | 445,681 |
| 2 | 23,086 | 23,106 | - | - | - | 46,192 |
| 3 | 955 | 950 | 944 | - | - | 2,849 |
| 4 | 2 | 2 | 2 | 2 | - | 8 |
| 5 | - | - | - | - | - | - |
| Total: | 469,724 | 24,058 | 946 | 2 | - | 494,730 |



Bare Earth DEM

- Derived from Lidar Analyst.
- Includes Lidar points classified as Bare Earth.
- Lidar Tile Statistics:

| # of returns per pulse | Return Number | | | | | | Total |
|------------------------|---------------|--------|-----|---|---|---------|-------|
| | 1 | 2 | 3 | 4 | 5 | | |
| 1 | 292,142 | * | * | * | * | 292,142 | |
| 2 | * | 12,591 | * | * | * | 12,591 | |
| 3 | * | * | 637 | * | * | 637 | |
| 4 | * | * | * | 2 | * | 2 | |
| 5 | * | * | * | * | * | * | |
| Total: | 292,142 | 12,591 | 637 | 2 | * | 305,372 | |



Relative Elevation DEM

- Derived by subtracting Bare Earth DEM from First Return DEM utilizing ESRI Spatial Analyst
- White space indicates zero value and/or no data in Bare Earth DEM.



Classification Training

- Perform a “wall-to-wall” classification on 2006 Ortho Imagery using Feature Analyst.
- Training set identifies pervious (ground/vegetation) and impervious (structures/asphalt).
- Shadows are an issue.



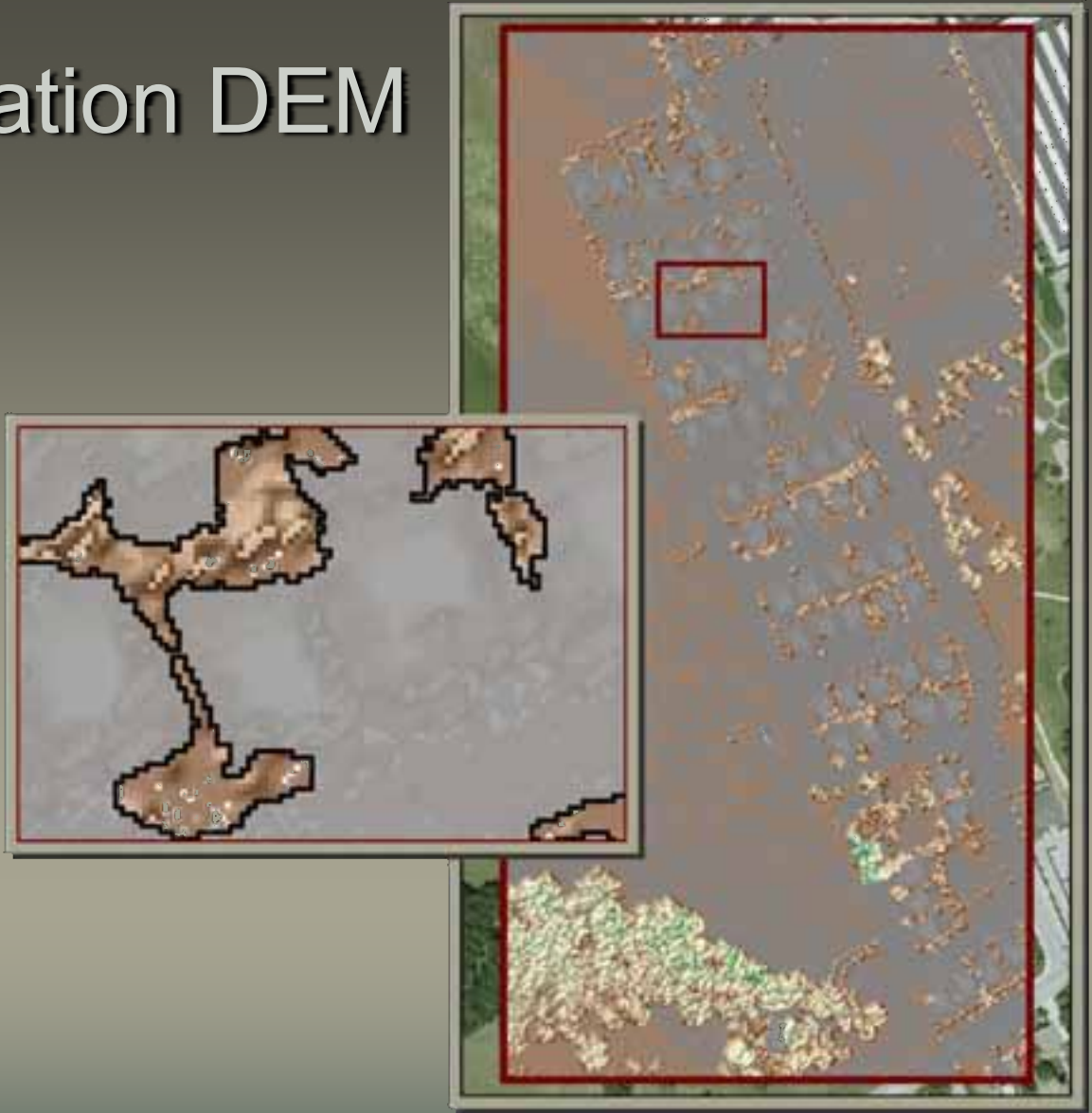
Impervious Classification

- Feature Analyst returns ground classification in two classes.
- Excellent discrimination, however some imprecision is inevitable.



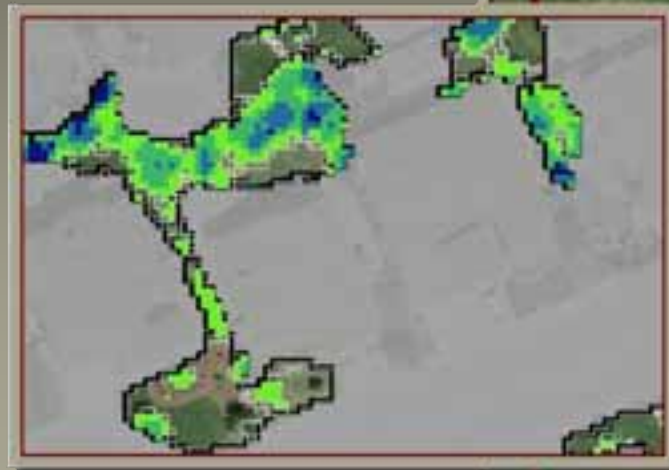
Pervious Elevation DEM

- Cells that are in the pervious layer are extracted using the raster calculator in ESRI Spatial Analyst.

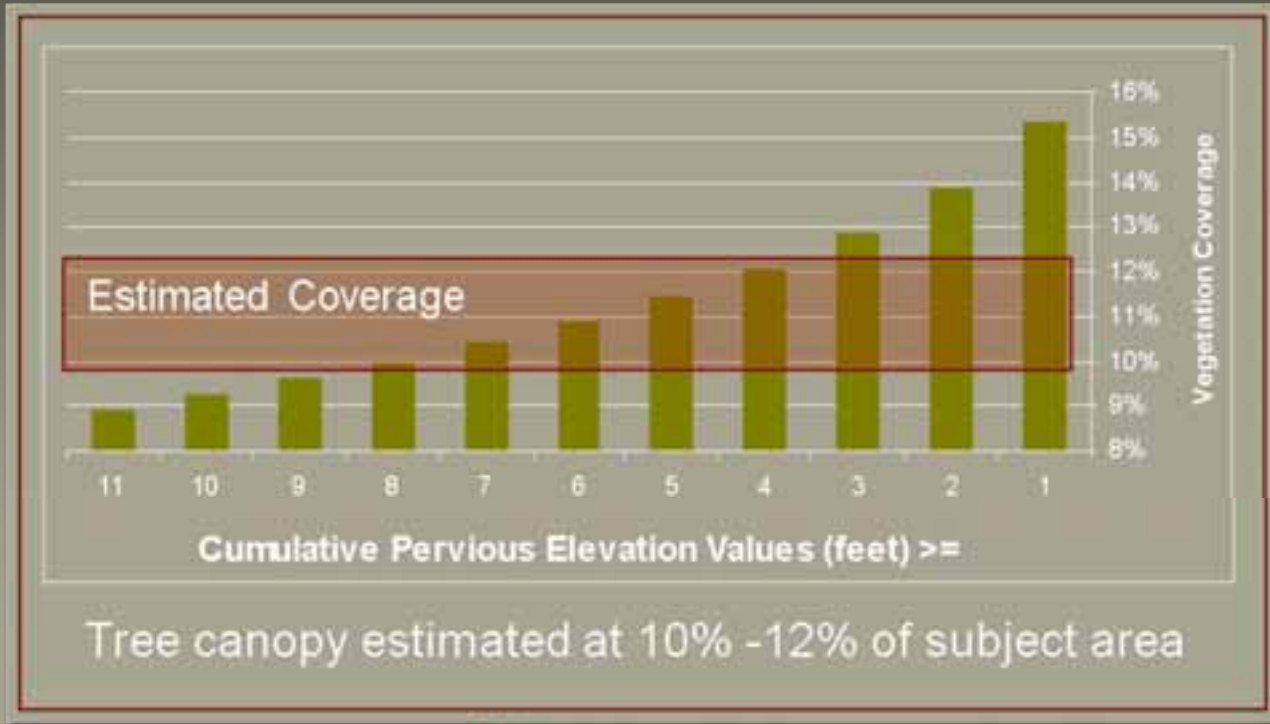


Classify Vegetation

- Raster elevation DEM in the pervious layer converted to feature class.
- Feature class is classified by elevation values.
- Identifies non-ground cover vegetation.



Estimated Tree Canopy



Summary

- Lidar analysis yields $\approx 6\%$ coverage and works best in urban areas.
- Ortho analysis yields $\approx 15\%$ coverage and works best in rural areas.
- Combined analysis yields $\approx 10-12\%$ coverage and works best in mixed areas.

