

# Vector-based Mobility Modeling

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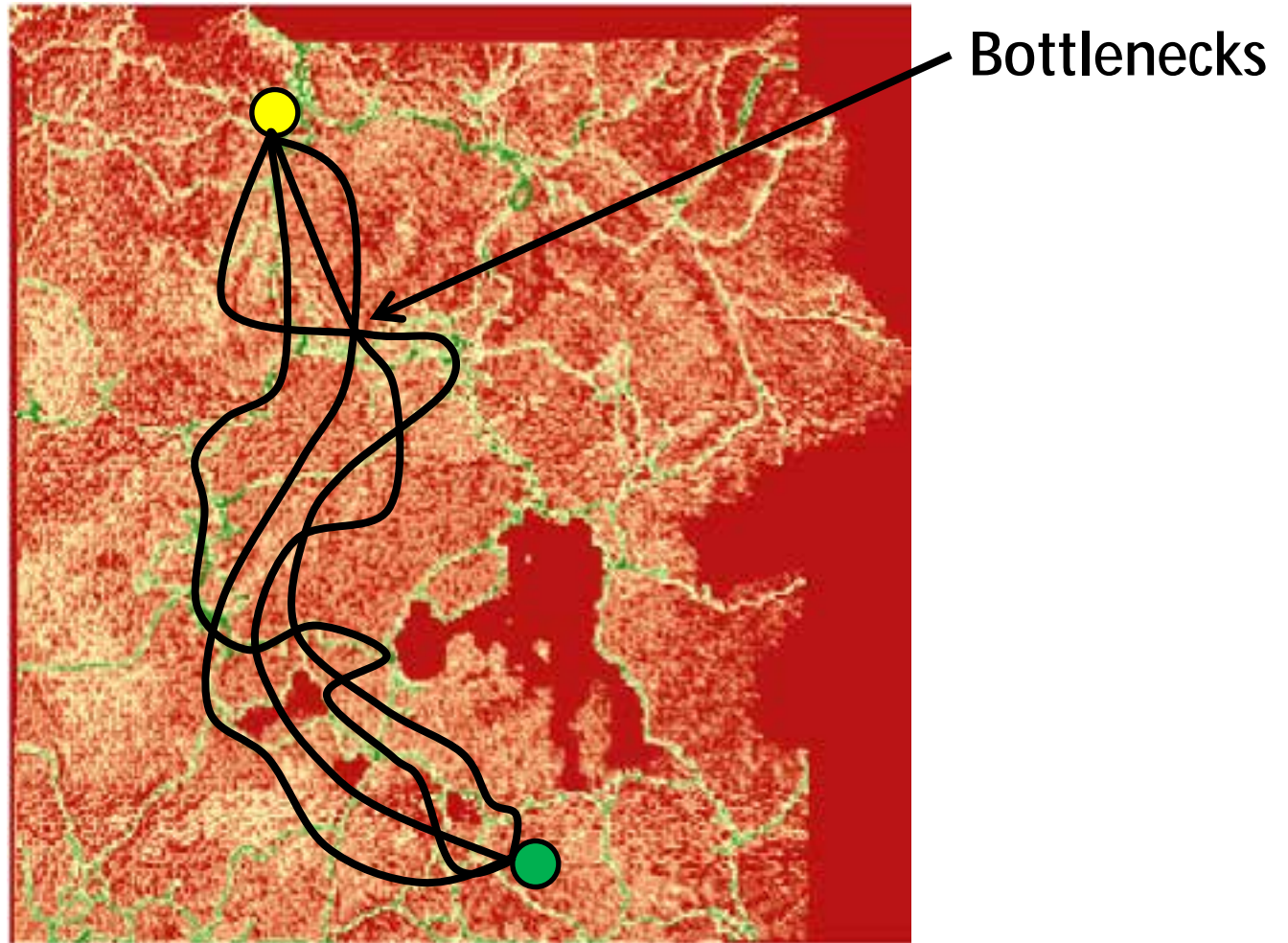
University of Redlands

Master of Science in GIS Program

# The problem

- To find areas on a terrain that could become potential bottlenecks for people moving across the terrain

# What are bottlenecks?



# Why are they important?

Areas to avoid

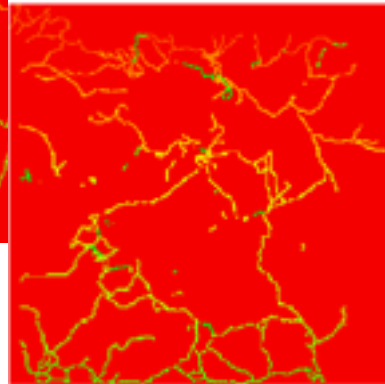
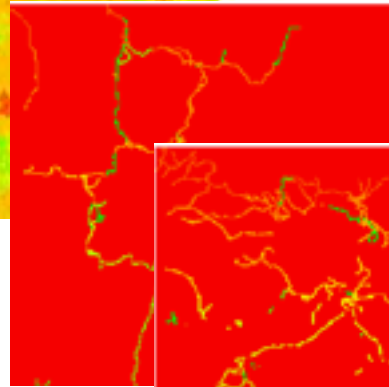
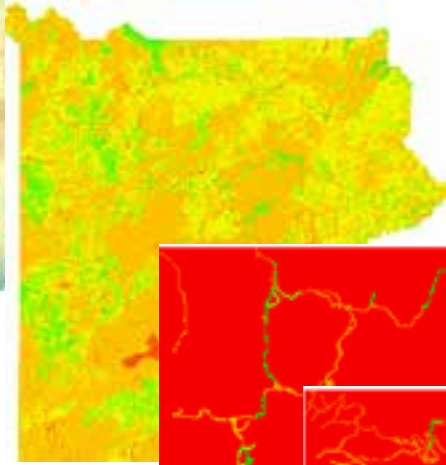
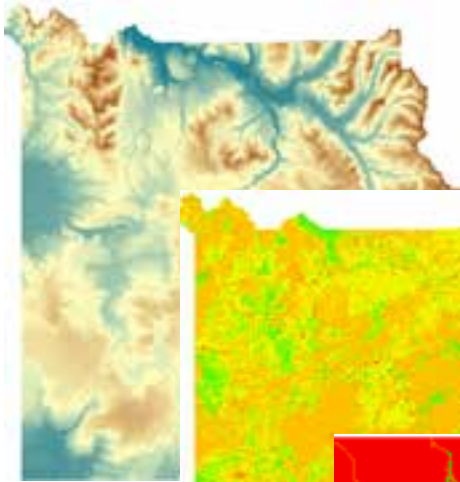




# The approach

- Consider many possible routes between points
  - Optimal (least cost path analysis)
  - Sub-optimal
    1. Build a cost surface
    2. Iteratively vary the cost surface
    3. Least cost path
    4. Repeat
    5. Visualize

# Step 1: Building the cost surface (pre-processing)



Elevation model

Land Cover

Roads

Trails

Posts

# Reclassification

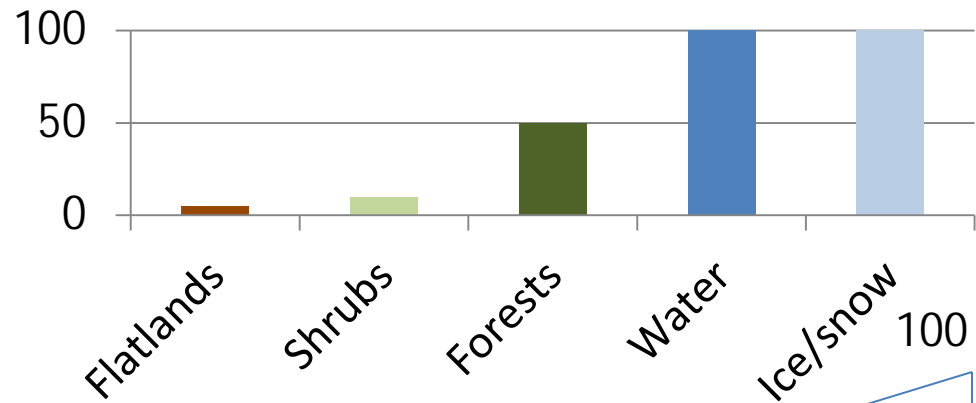
Trails and posts

0 if present, else 100

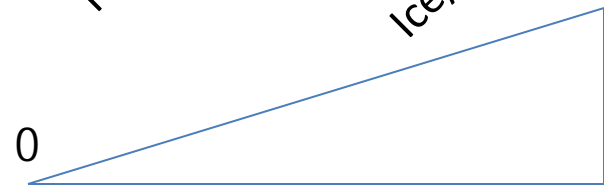
Roads and highways

0 if present, else 100

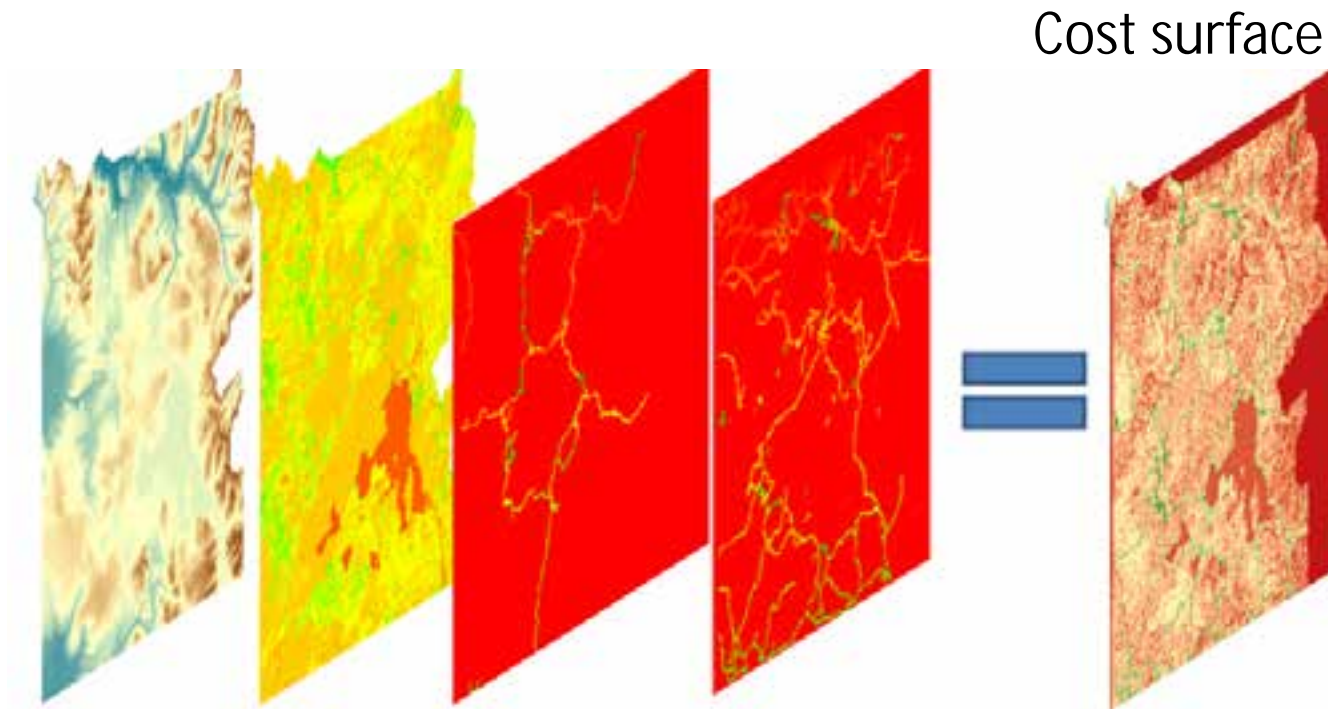
Land Cover



Elevation profile  $\Rightarrow$  Slope



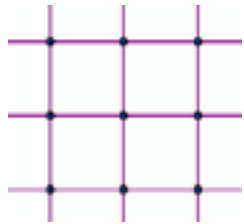
# Reclassification and weighted overlay



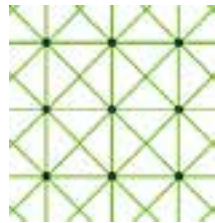


# Step 2: Vector based re-sampling

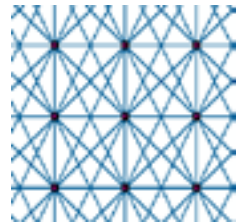
- To speed up simulation
- Consider a regular grid of points connected by edges



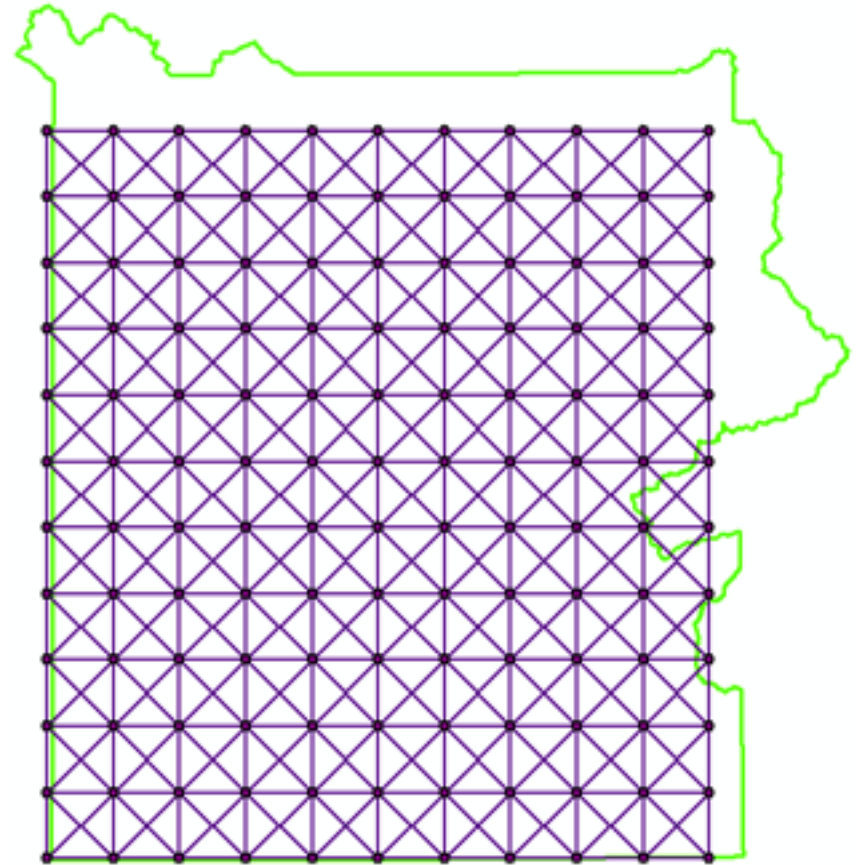
Rook



Queen



Knight

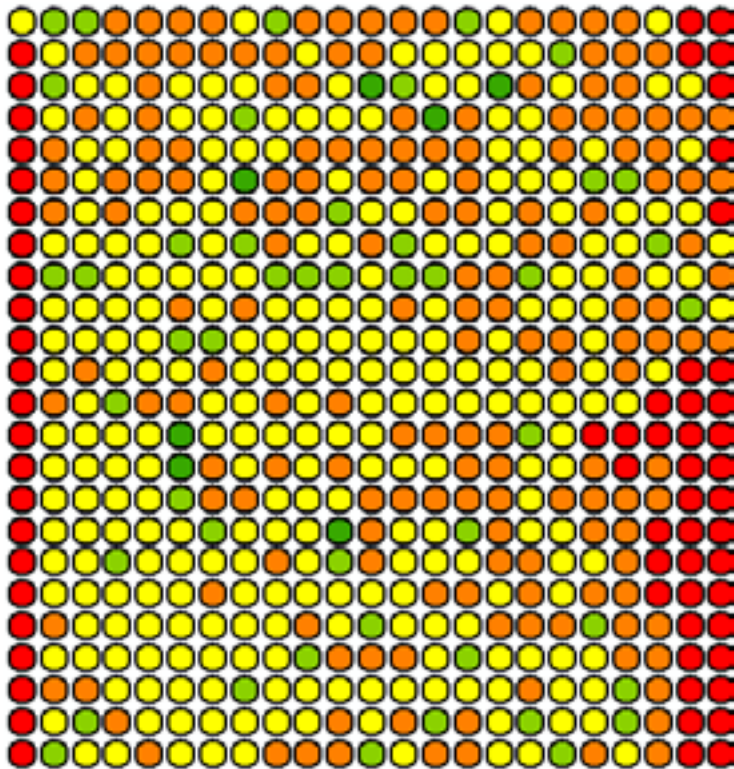


# Step 3: Least cost path analysis

- Faster when run on a lower resolution vector model instead of a raster
- Ability to record every traversed edge and node
- Ability to model complex constraints
  - With the use of ArcGIS Network Analyst Extension

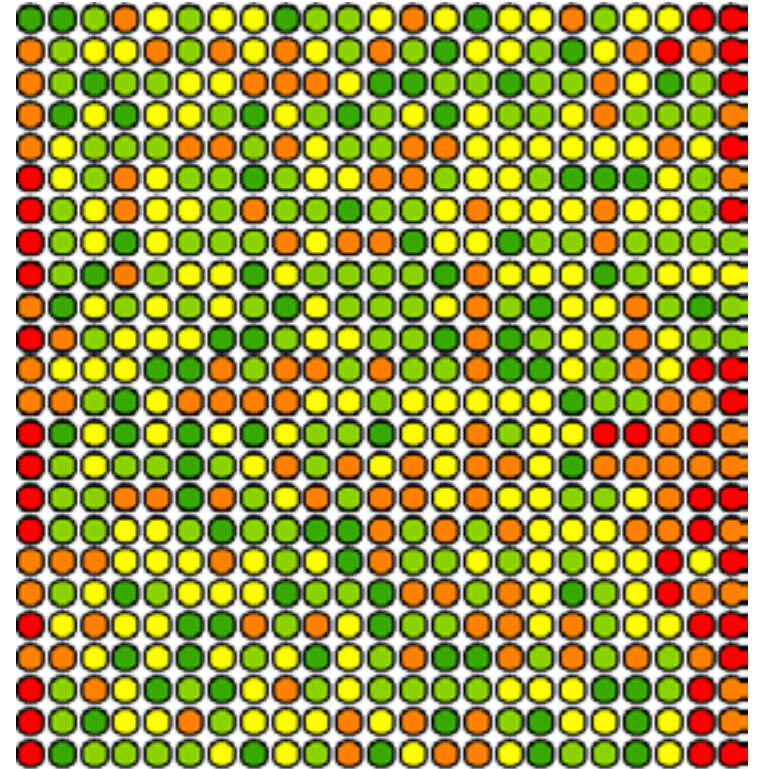
# Step 4: Apply noise to vary the surface

Before



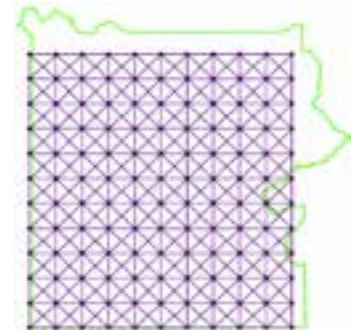
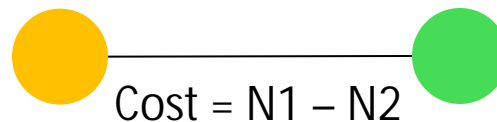
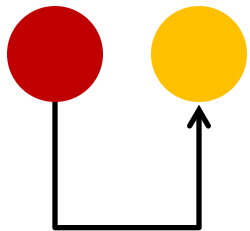
$\pm 20\%$

After



# Step 5: Re-compute edge & repeat LCPA

- Cost of traversing an edge is the difference in costs of the adjoining nodes
- When noise is added to the node value the cost of the edge varies
- Re-build the network dataset



# Step 6: Store traversed edges

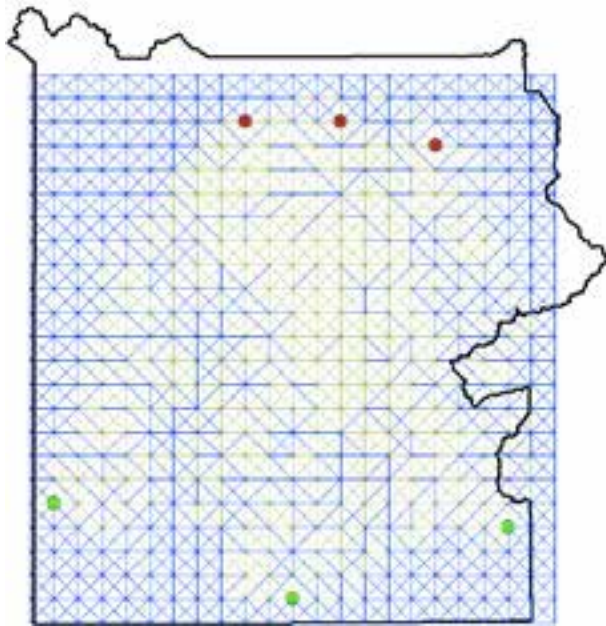
- Track the occurrence of each edge in all the traversed routes

edges

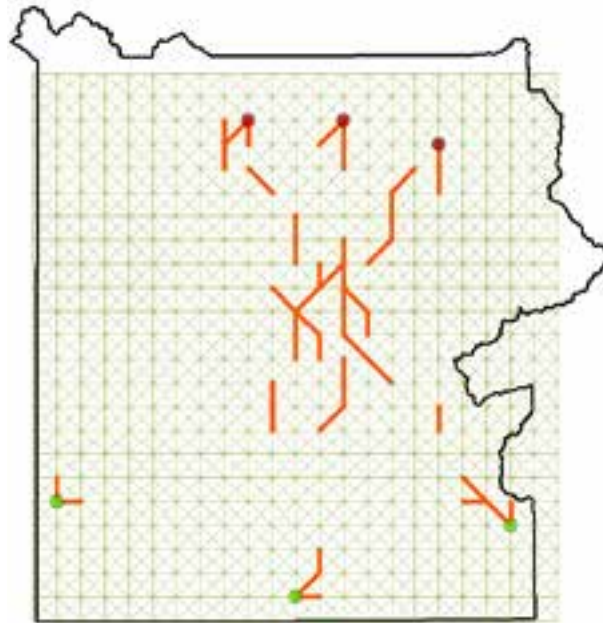
|  | OBJECTID * | SHAPE *    | Id | SRC_ID | DES_ID | COST  | REPEATED | ETYPE | SHAPE_Length |
|--|------------|------------|----|--------|--------|-------|----------|-------|--------------|
|  | 64         | Polyline M | 0  | 34     | 10     | 0     | 0        | 2     | 5939.696962  |
|  | 65         | Polyline M | 0  | 35     | 34     | 10    | 300      | 1     | 4200         |
|  | 66         | Polyline M | 0  | 35     | 12     | 115   | 0        | 1     | 4200         |
|  | 67         | Polyline M | 0  | 35     | 13     | 0     | 3        | 2     | 5939.696962  |
|  | 68         | Polyline M | 0  | 35     | 11     | 28.28 | 0        | 2     | 5939.696962  |
|  | 69         | Polyline M | 0  | 36     | 35     | 20    | 56       | 1     | 4200         |



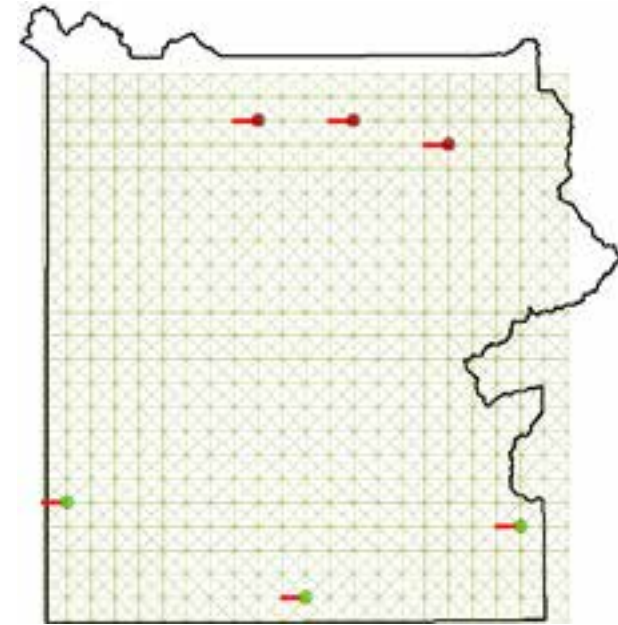
# Step 7: Visualize result



Edges not traversed at all



Edges with high traversal



Edges with highest traversal



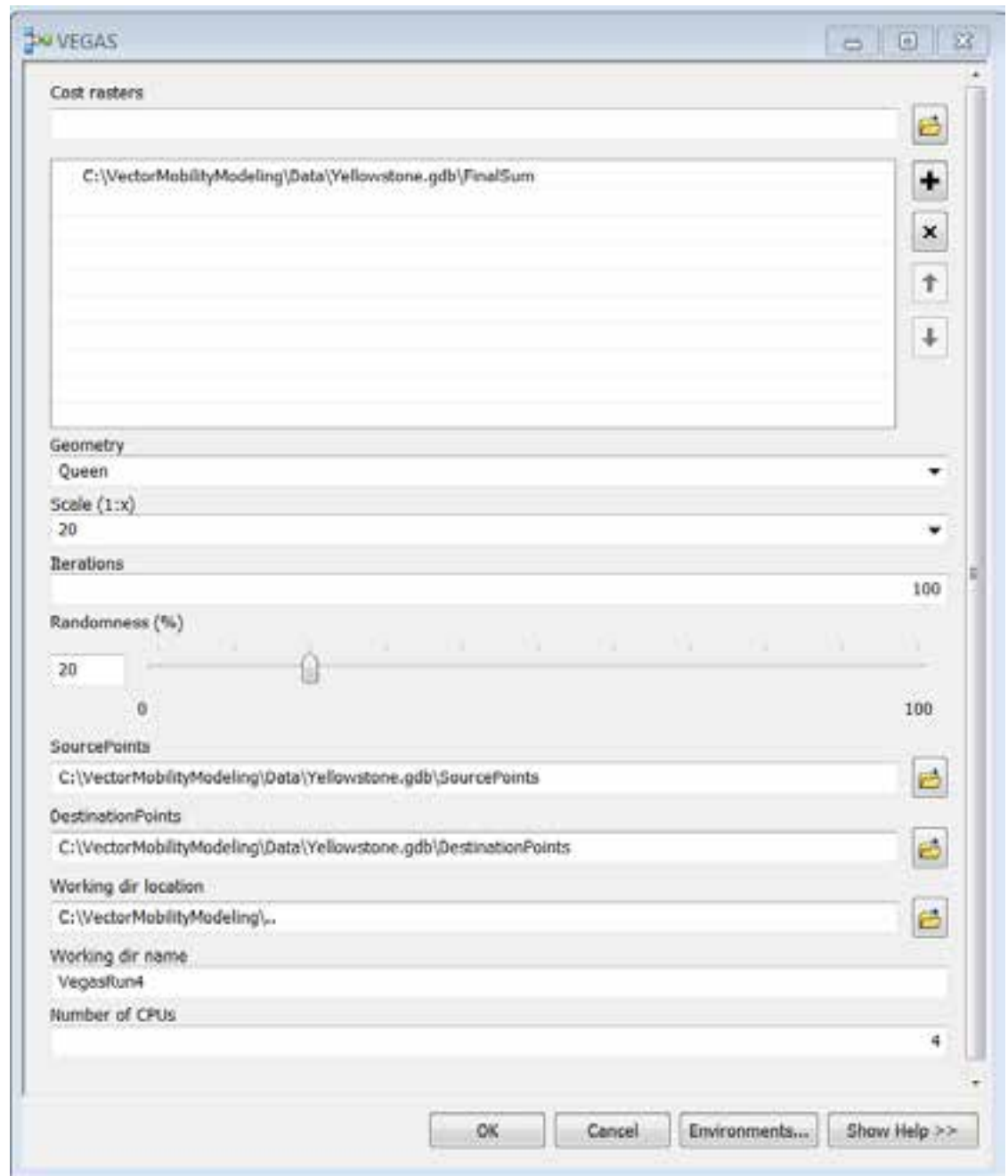
# The model

Raster  
surfaces

Geometry,  
Scale,  
Iterations,  
Noise

Source and  
Destination

Working dir.,  
Cores

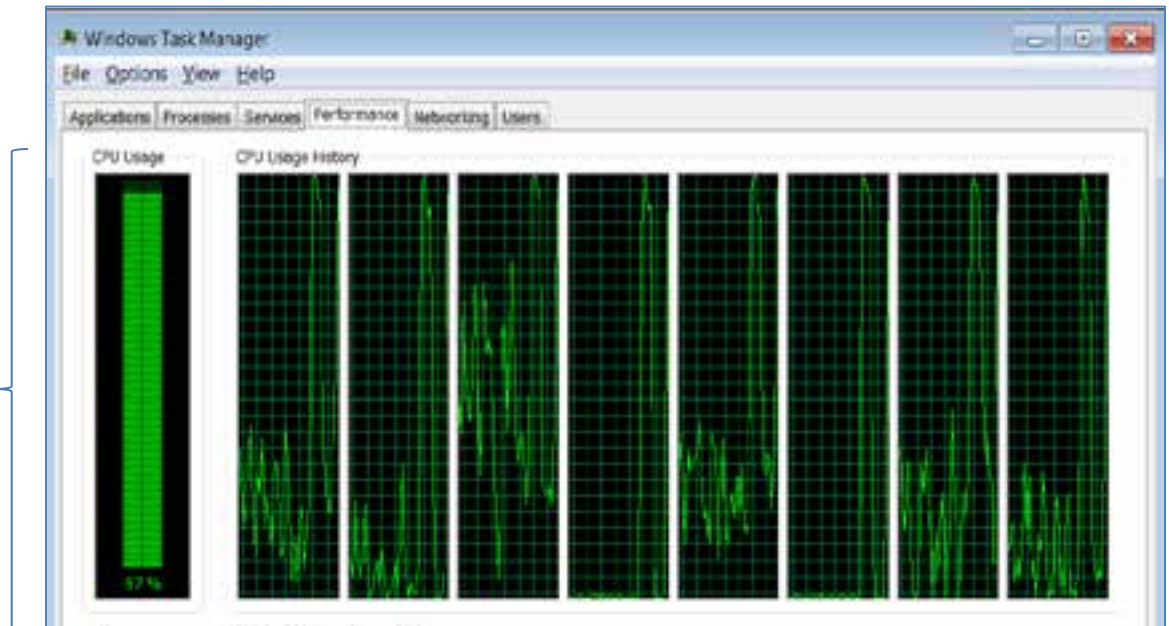


# About the tools

- Python scripts
  - Using arcpy and Network Analyst Extension
  - Run be run within ArcMap as a Model
  - Python API
- Runs simulation of routes in multi-processing manner for efficiency

# Multi-processing

| Name      | Date modified     | Type        |
|-----------|-------------------|-------------|
| vegas.gdb | 10/7/2013 9:21 PM | File folder |
| worker0   | 10/7/2013 9:21 PM | File folder |
| worker1   | 10/7/2013 9:21 PM | File folder |
| worker2   | 10/7/2013 9:21 PM | File folder |
| worker3   | 10/7/2013 9:21 PM | File folder |
| worker4   | 10/7/2013 9:21 PM | File folder |
| worker5   | 10/7/2013 9:21 PM | File folder |
| worker6   | 10/7/2013 9:21 PM | File folder |
| worker7   | 10/7/2013 9:21 PM | File folder |

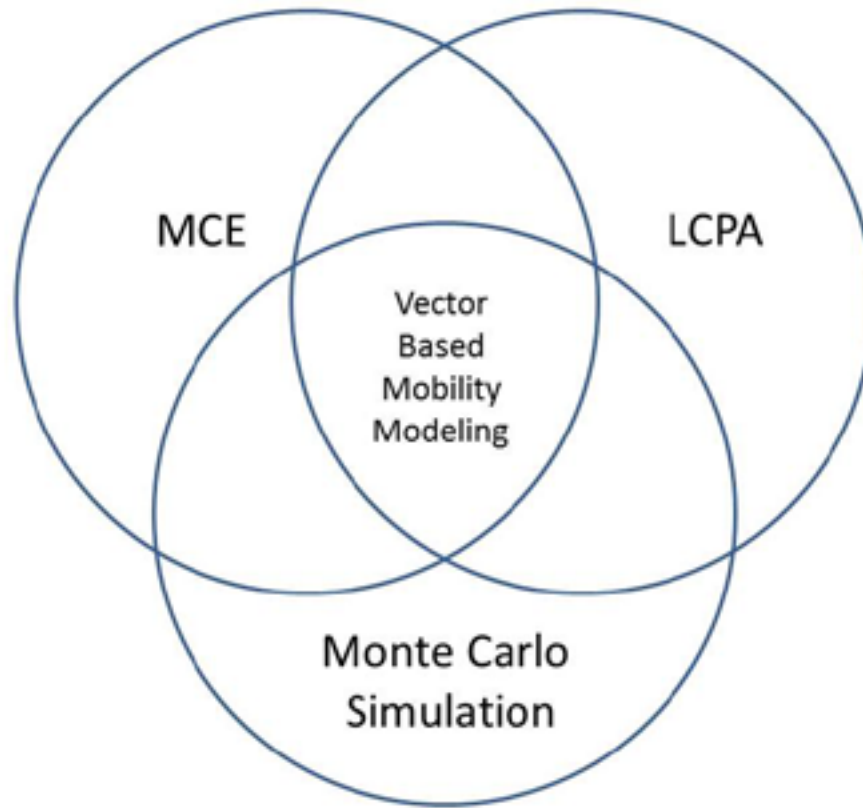


~100% CPU

# Applications

- Troop mobility
- Congestion mapping in transportation
- Troop positioning in guarding facilities
- Rescue mission planning
- ...

Thank you



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