



# Use of Mobile LiDAR for Asset Management:

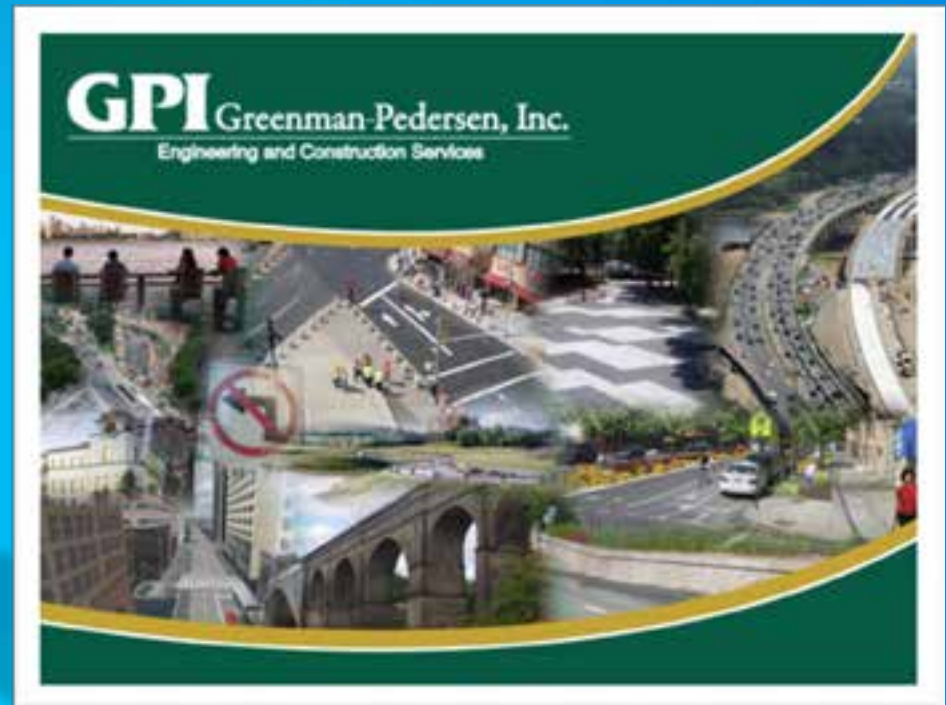
*How MassDOT Took an Innovative Approach  
to Sign Assessment Inventory of Sign Assets*

**Mark Day**

*Director of Application Development*

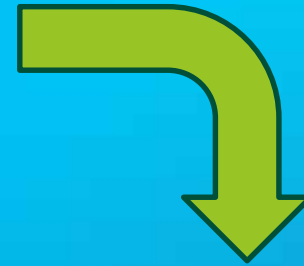
# About Greenman-Pedersen, Inc (GPI)

- Multi-discipline engineering firm
- Established in 1966
- 1100 employees
- 20 offices
- Transportation Asset Management



# Project Overview

- **Traffic Sign Asset Management Project**
  - Massachusetts DOT
  - Inventory of all signage on state-owned routes (6,000 Centerline Miles)
  - Night-time Retro-reflectivity condition
  - Implement Asset Management System
  - Tie into existing Maximo system
  - 2 Year Project



# GPI Proposal

- GPI has completed over 50 similar projects
- Use high-res LiDAR / high-res images to conduct inventory
- Value Added Proposition.  
*Drive it once*
  1. Additional Assets
  2. Visualization
  3. Survey Grade Areas



# LiDAR 101: What is LiDAR?

- Light Detection and Ranging
- Position of the LiDAR provided by GPS
- Position and Orientation of the laser provided by IMU
- The scan angles and ranges of the laser are provided by the sensor
  - Data post processed to accurately determine the position of each point
  - Acquisition:
    - *Aerial 400K pps*
    - *Mobile 1.2 Million pps*
  - Density:
    - *Aerial: 2-100 ppsm*
    - *Mobile: 2000-5000 ppsm*
- Point Cloud Data File



# Types of LiDAR

Terrestrial

Airborne

Mobile

- Survey Grade
- Mapping Grade

# Data Collection

## RIEGL VMX450

### RIEGL VMX450

- 1,100,000 measurements per second
- Dual 360 FOV Scanners
- 5000 points per sq. meter



### NIKON D810

- 36 MP Highest Resolution ML Calibrated Video/Still
- Mapping Camera

## NIKON D800



# Mobile LiDAR for Roadways

Survey Grade Scanners

Riegl VMX 450

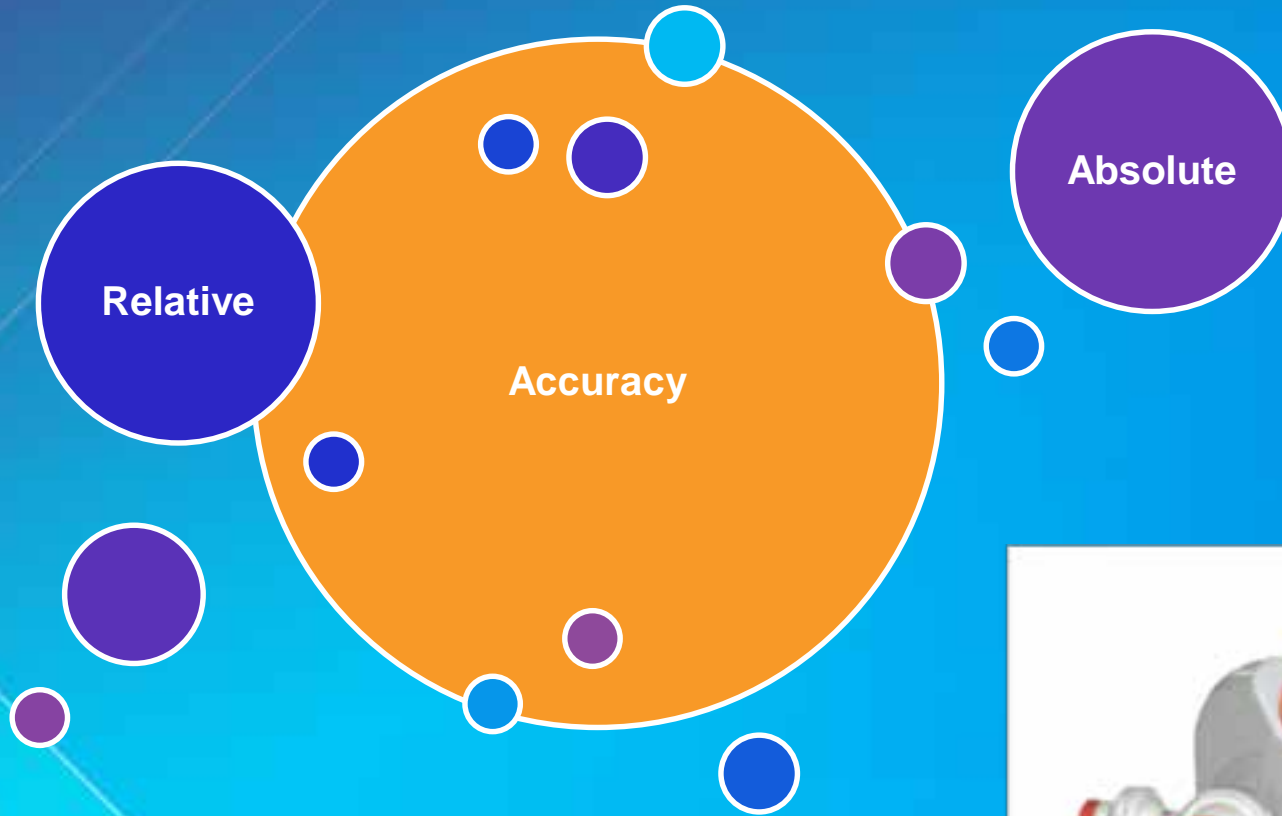
High Scan Rate = Very large data files

Result: Complex / adoption is limited

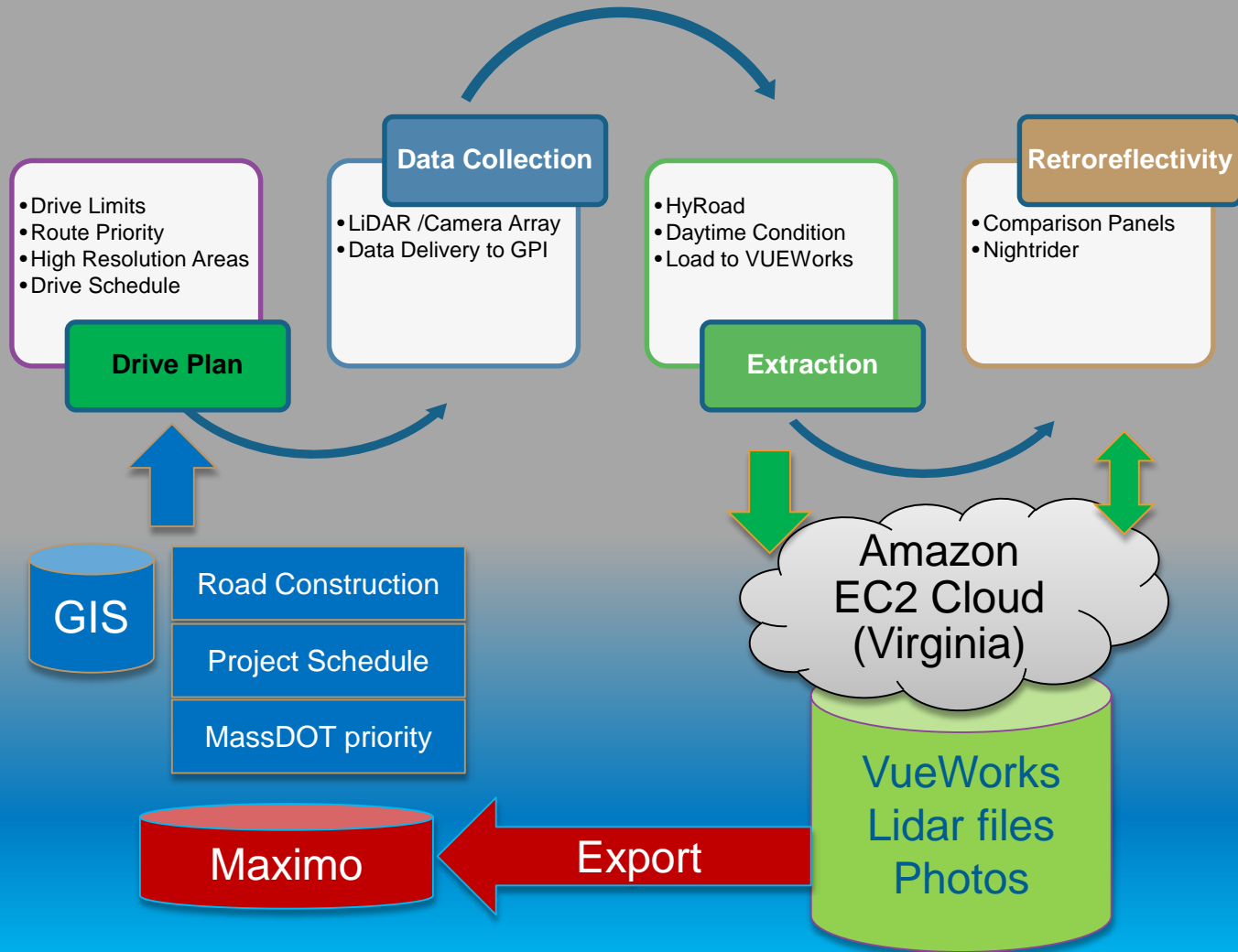




# “Survey Grade Scanners”



# Project Overview



## Data Details

- Inventory approximately 250,000 signs
- Dataset is over 50 TB
- 40 TB LiDAR
- How to deal with it?



## The Old Way

- **Data Extractors navigate through imagery to find assets.**
- **Work in small sections**
- **Cut cross sections**
- **Perform measurements / assessment**
- **Time consuming / Unorganized**

# Wouldn't it be nice to.....

**Navigate seamlessly through the  
point cloud**

# Wouldn't it be nice to.....

**View imagery and LiDAR  
in concert**





**Wouldn't it be  
nice to.....**

**Speed up extraction**

Wouldn't it be  
nice to.....

**ILMF**





# Solution

- **Worked with gaming company to develop a Programming Interface**
- **Developed Custom Extraction software: HyRoad**

# HyRoad Software Demonstration



## Current Project Status

- **Extracted over 100,000 signs**
- **Night Assessed Over 55,000 signs**
- **Driven over 40% of project**
- **Driving District 3 & 6**



## Realized Benefits

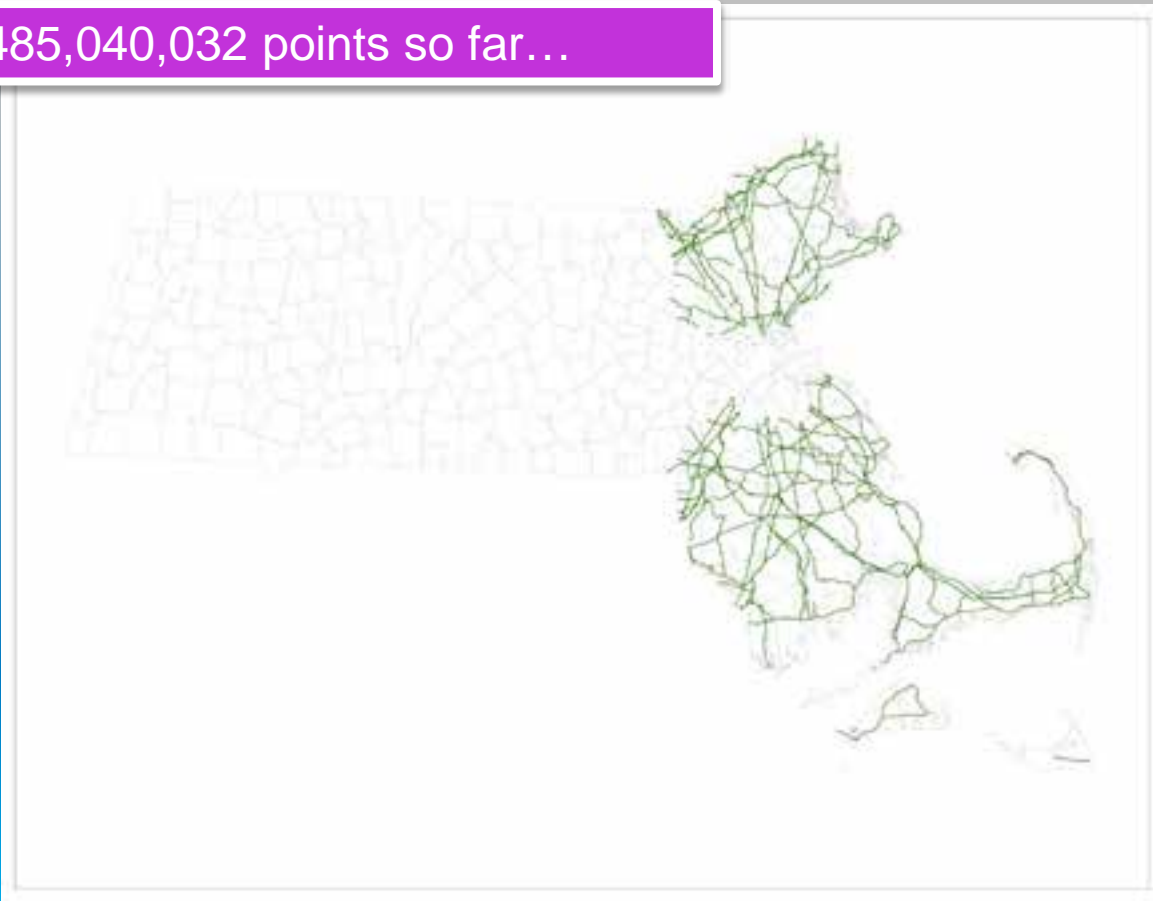
- **Ease of locating signs in point cloud**
- **Increased extraction accuracy**
- **Can view entire dataset in a single project**
- **20:1 Compression at 3cm**
- **Opened several possibilities for data visualization**

## Lessons Learned

- **Compression allows for new horizons**
- **50 TB is easy to say**
- **Processing....Procedures need to be altered**
- **Work with good partners**

# Demo

688,978,485,040,032 points so far...



# Questions

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