



Point Clouds and 3D Mesh

Sean William Morrish, ESRI Redlands

Thomas Other, ESRI R&D Center Zürich

Complementary Resource Email

(no marketing)

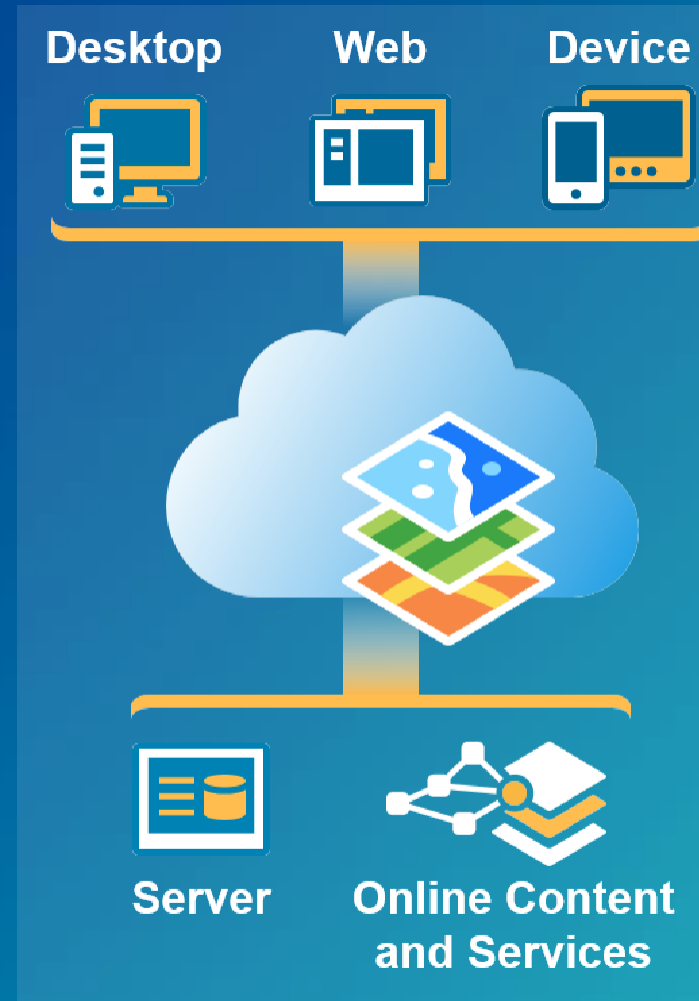
- A copy of the presentation
- Links to today's web demos
- Links to training materials



Agenda

1. 3D Data on the ArcGIS Platform
 - Introduction to different 3D Scene Layers
 - Indexed 3D Scene Layers
2. 3D Data on the Desktop
 - Data Acquisition & Processing
 - Data Publishing & Value Add
3. 3D Data on the Web
 - Data Viewing & Authoring
 - Current & Future Features

ArcGIS Platform



Indexed 3D Scene Layers — *Fundamentals*

- Stream data format designed to support 3D geospatial content
- Provides level of detail using advanced tree traversal algorithms
- Supports different layer types and data profiles
- Uses request scheduling to achieve optimal performance
- Open standard: [I3S Spec](#)

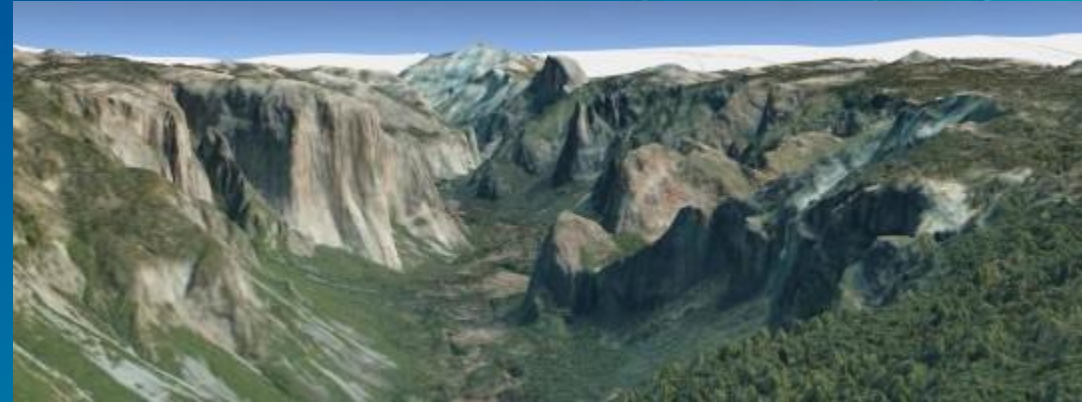
Indexed 3D Scene Layers — *Layer Types*

3D Objects



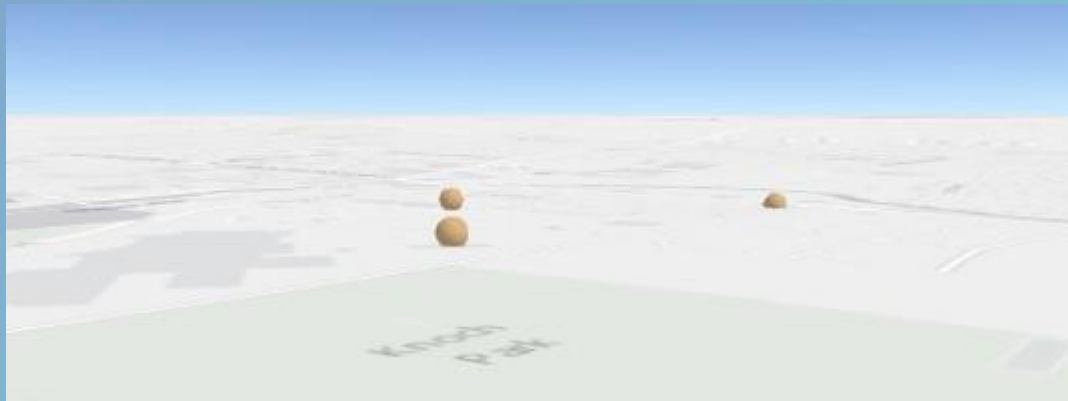
Multipatch

3D Integrated Mesh

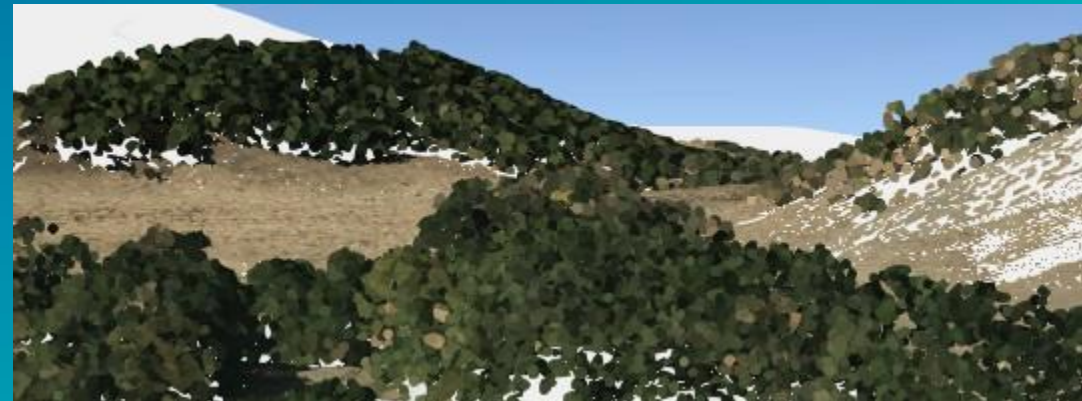


VRICON / Drone2Map

3D Points

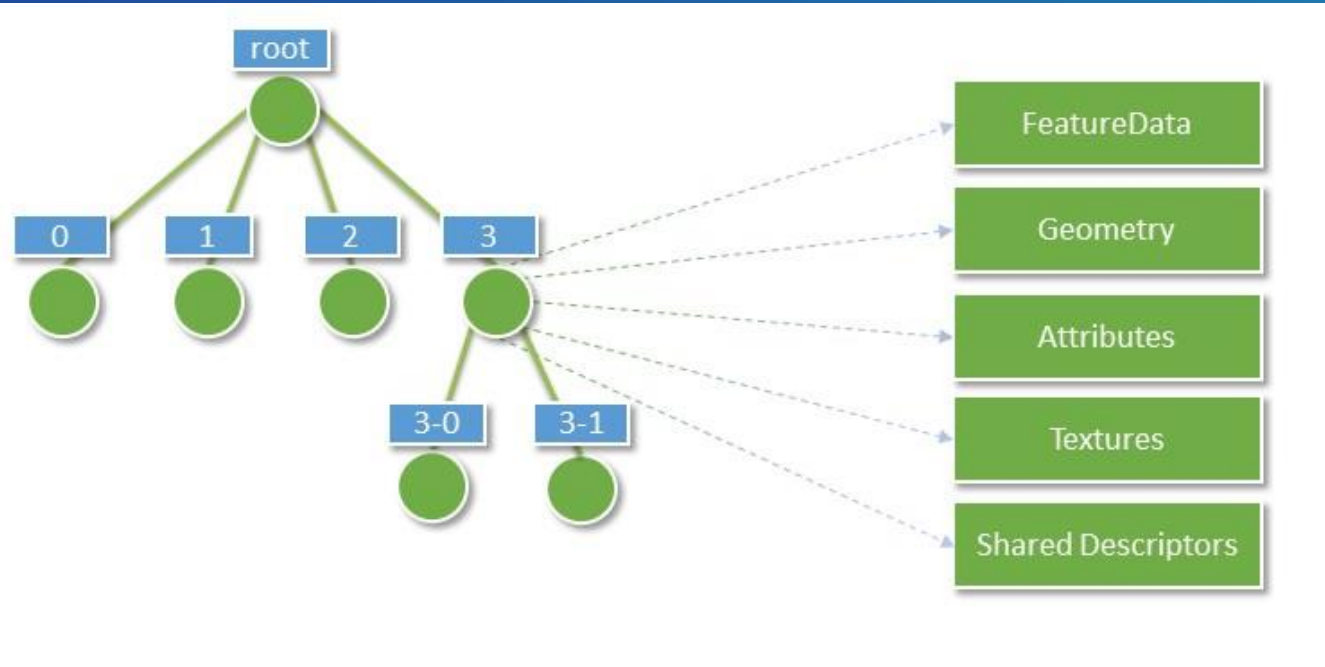


Point Clouds



LAS

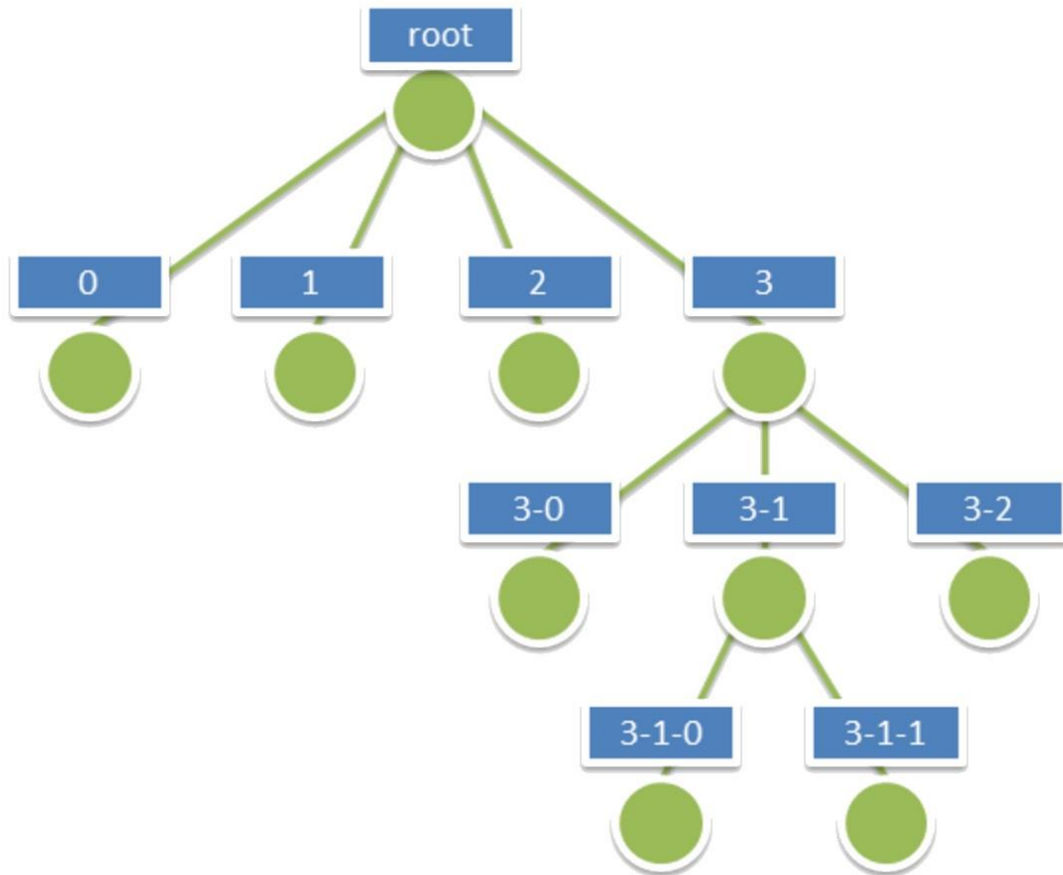
Indexed 3D Scene Layers — *Data Format*



- Data is clustered in LOD nodes
- Each node contains relevant data on
 - Features
 - Attributes
 - Geometry
 - Textures

Indexed 3D Scene Layers — *Level Of Detail*

Node Structure

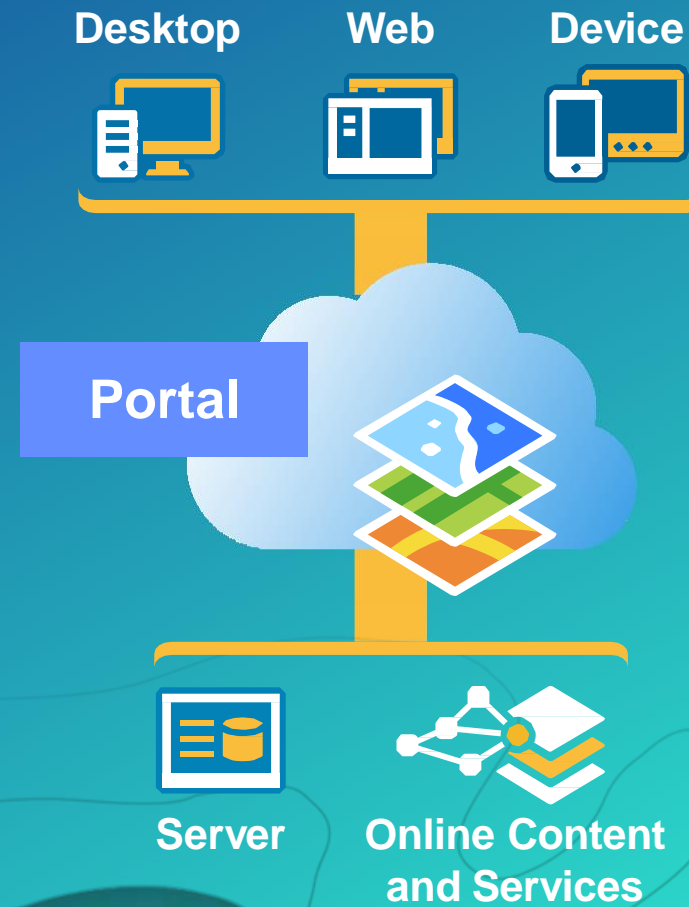


3D Data on the Desktop

The background of the slide is an abstract composition. The upper two-thirds of the image are filled with a textured, wavy pattern in shades of orange and red, resembling crumpled paper or a topographical map. The lower third of the image features a dark blue, wavy border that separates the orange section from a bottom area containing a lighter blue grid pattern, which looks like a stylized city street map or a data visualization.

3D GIS Platform

- Synthesize 2D and 3D in web GIS architecture
- Default Elevation Service
- Multiuse dynamic services across clients
- Securely manage large enterprise geodatabases
- Analyze across real-time and historical data



ArcGIS 3D Scene Layers

- 3D Objects Scene Layer
- 3D Point Scene Layer
- 3D Integrated Mesh Layer
- 3D Point Cloud Scene Layer
- Elevation Layer



Esri Indexed 3d Scene (*.I3s) and Scene Package (*.slpk) formats

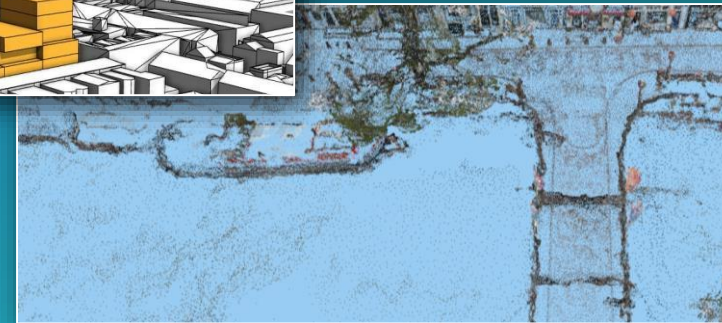
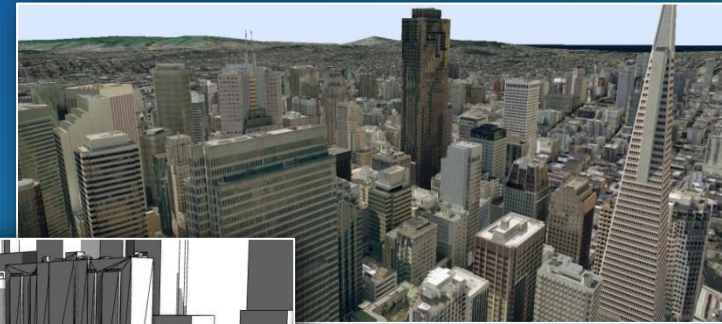
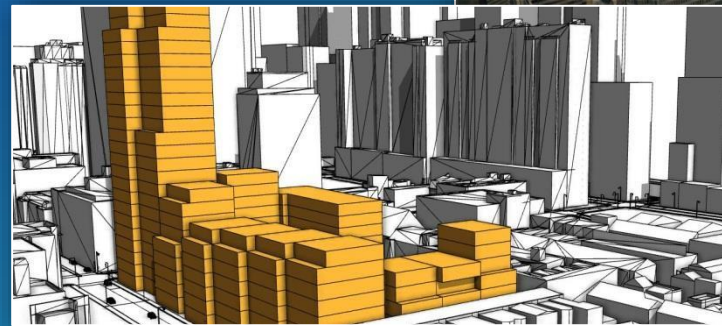
Requirements for a 3D GIS visualization format:

1. **Web friendly:** JSON + Typed Arrays
2. **Mobile friendly:** Works good with varying bandwidth
3. **Extensible:** Support different types of content
4. **Declarative:** Reduce required implicit knowledge
5. **Efficient:** Use spatial indexing for quick delivery
6. **Scalable:** Provide Level of Detail Support
7. **Protected:** Ensure that content is protected
8. **Open:** Full Specification publicly accessible

Now available @ <https://github.com/Esri/i3s-spec>

Content Profiles

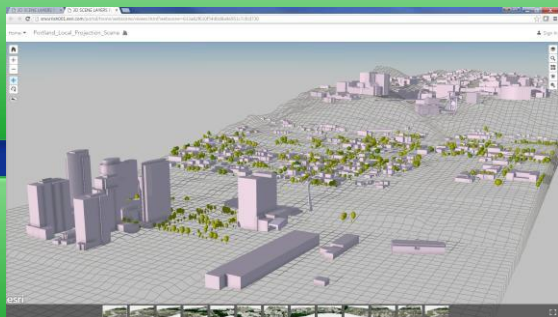
- Support different geometry types
 - Individual Features
 - Points
 - Multipatches
 - Integrated Meshes
 - Pointclouds
 - Point Symbols
 - Analytics



Parts of a Scene

Feature Service Layers
*(< 2000)

Web Scene Layers
(i3S)



2D Layers
Draped or Absolute*

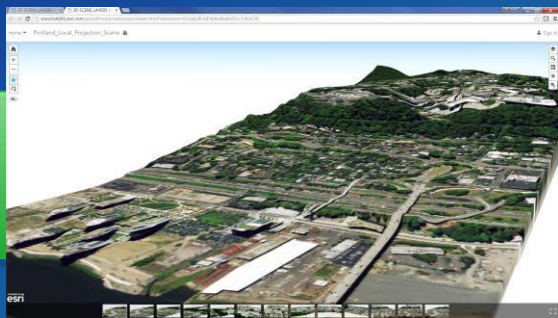
3D Layers
(Absolute Z')



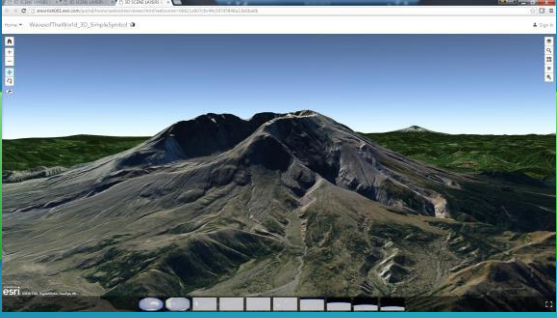
Feature Service Layers
*(< 2000)

Web Scene Layers
(i3S)

Your Local Imagery

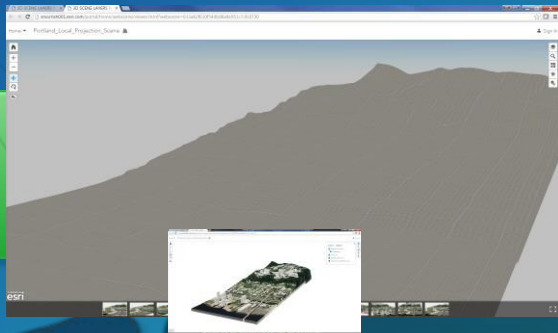


Draped Imagery

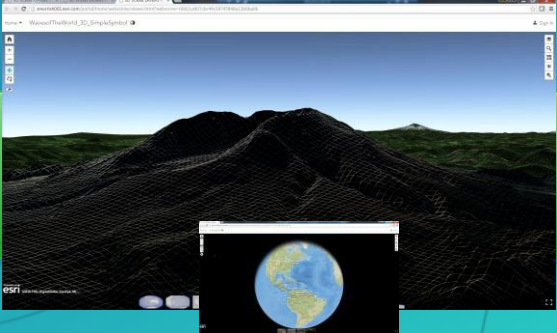


ArcGIS Online

Your Local Terrain



Terrain

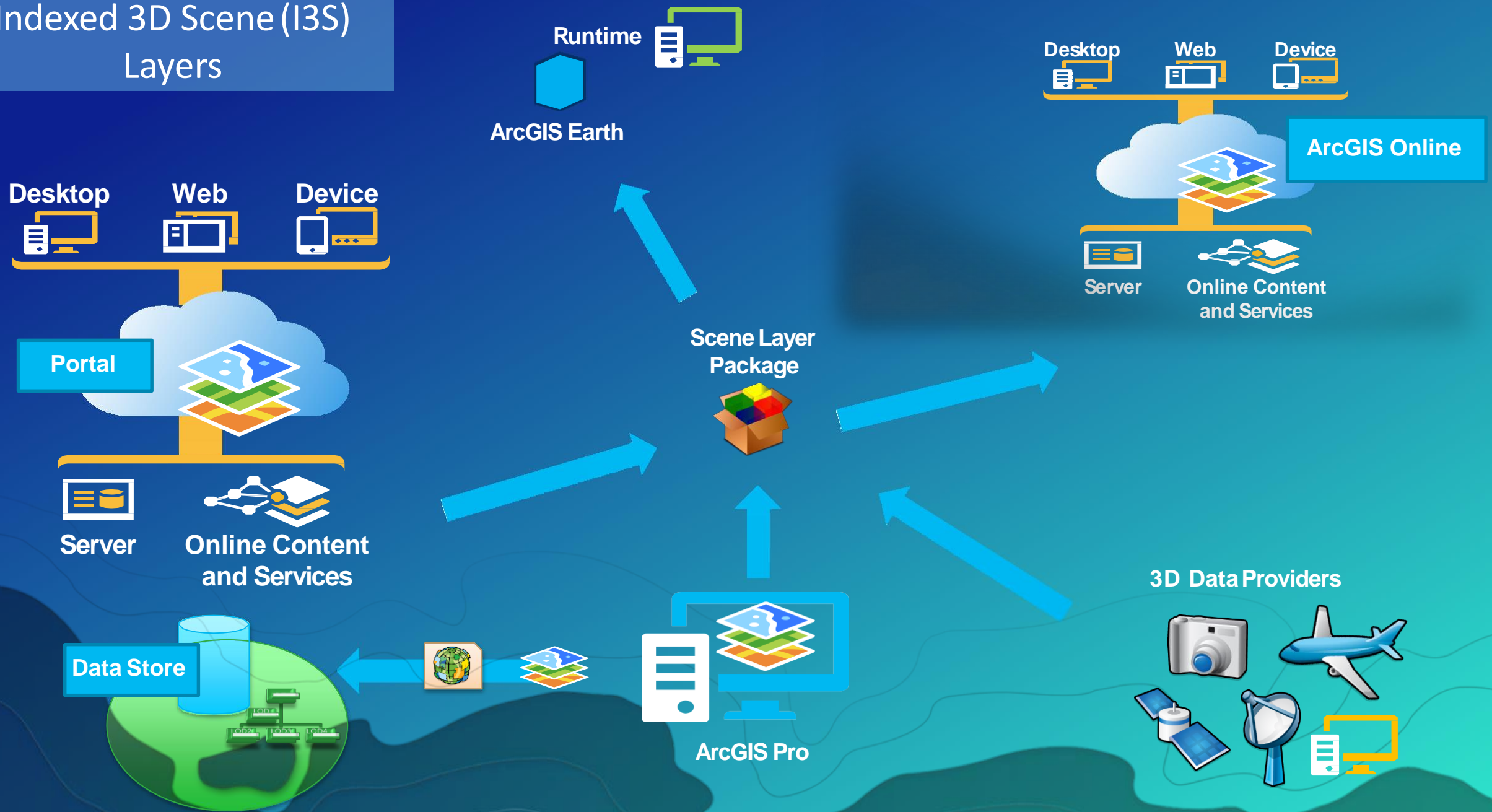


ArcGIS Online

Local Scene

Global Scene

Indexed 3D Scene (I3S) Layers



Point Clouds

What are Point Clouds

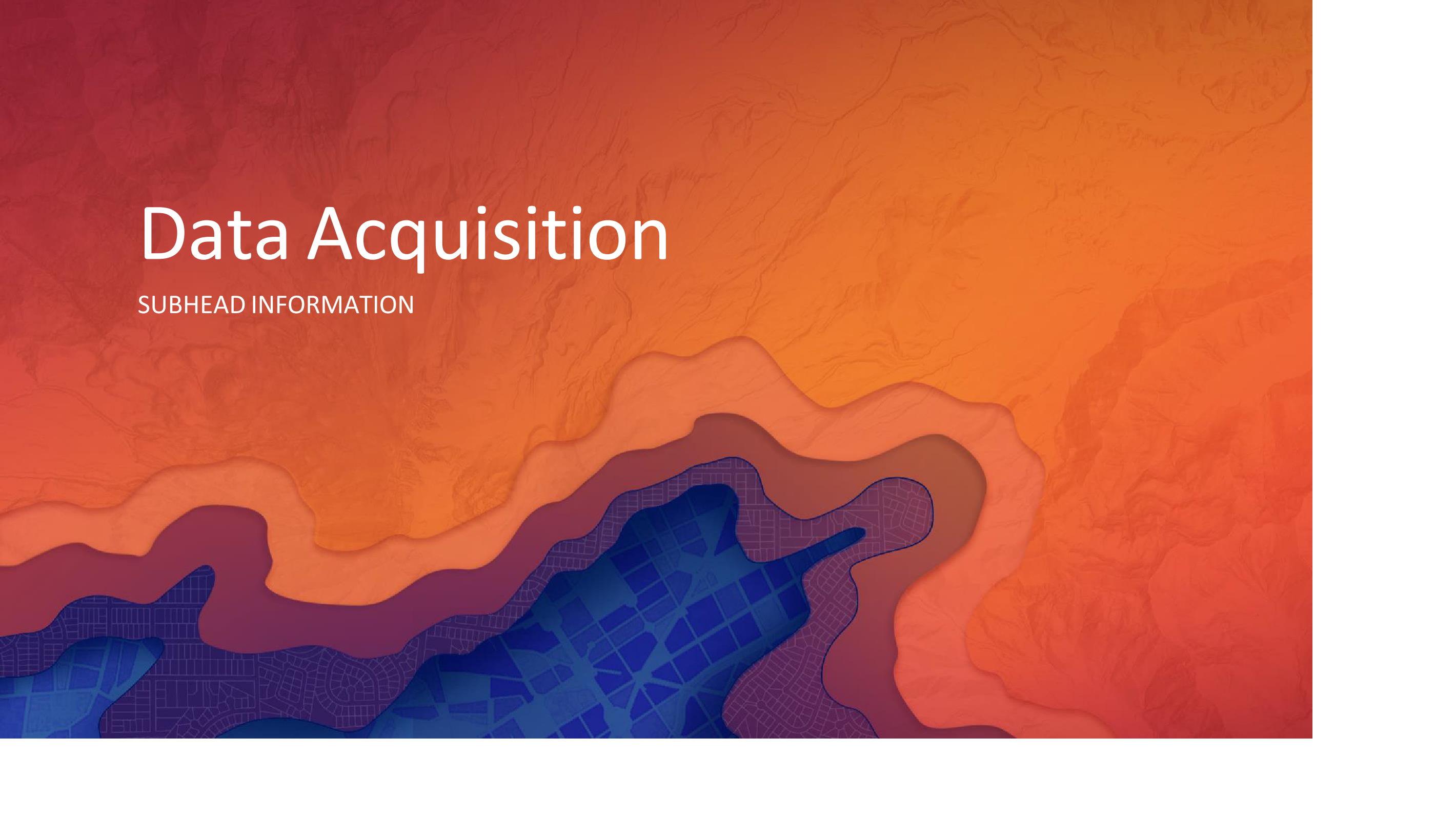
Integrated Mesh

What is an Integrated Mesh



Data Acquisition

SUBHEAD INFORMATION

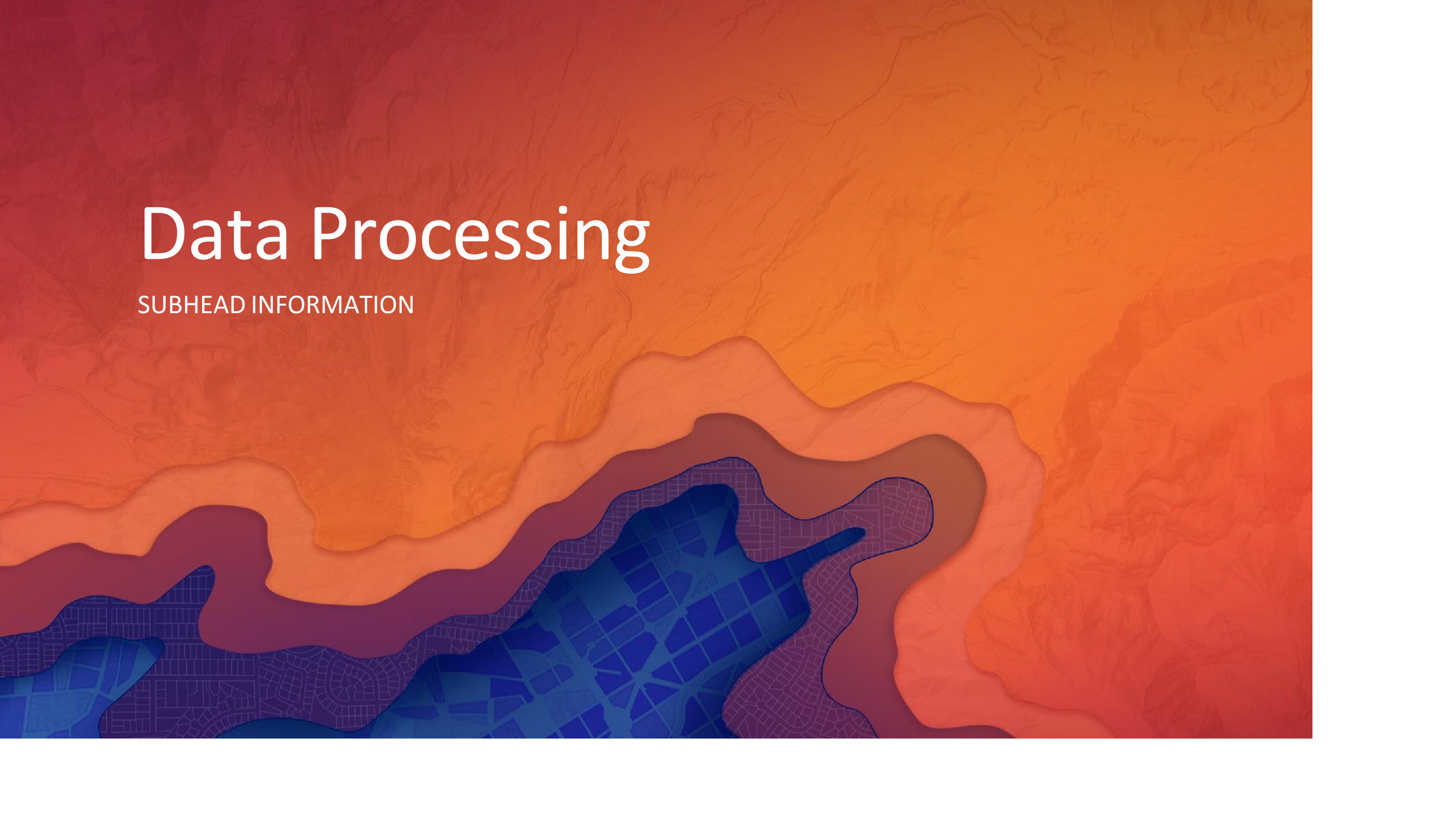


Data Acquisition

Platforms for the collection of LiDAR and Integrated Mesh data.

Data Processing

SUBHEAD INFORMATION



Data Processing

Workflows to process, create and analysis LiDAR & Integrated Mesh data.

Publishing

SUBHEAD INFORMATION

Publishing

Workflows for the sharing and publishing of LiDAR and Integrated mesh data.

Value Add

SUBHEAD INFORMATION

Added Value of LiDAR & Integrated Mesh

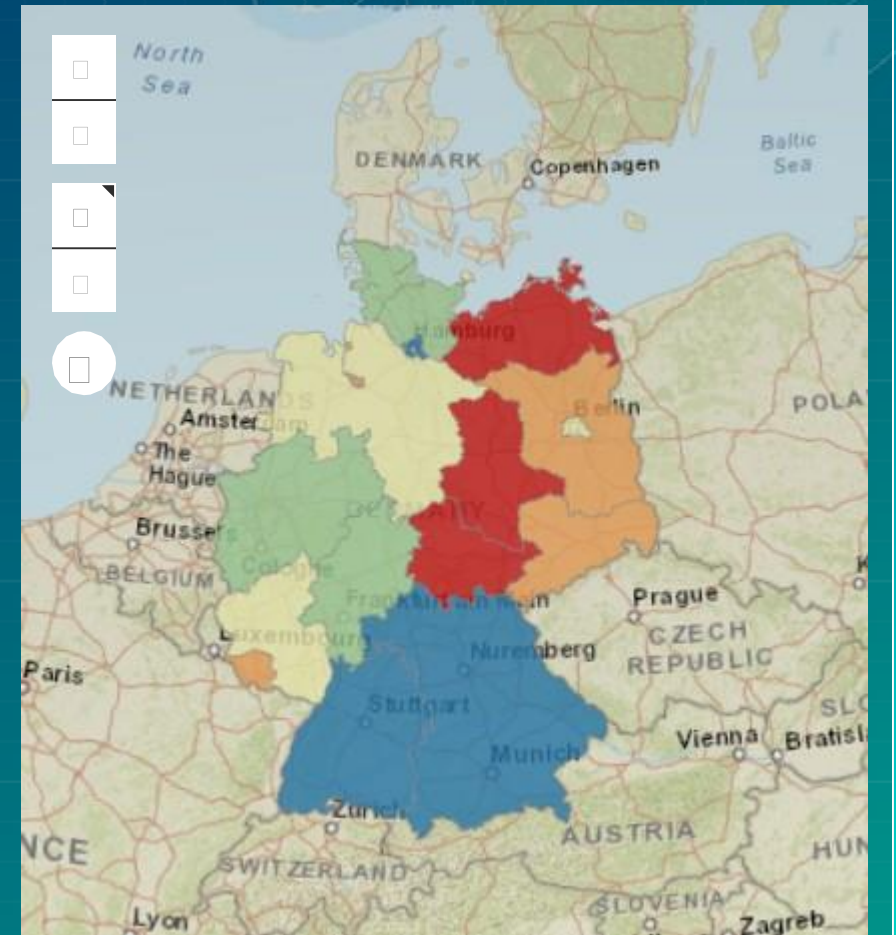
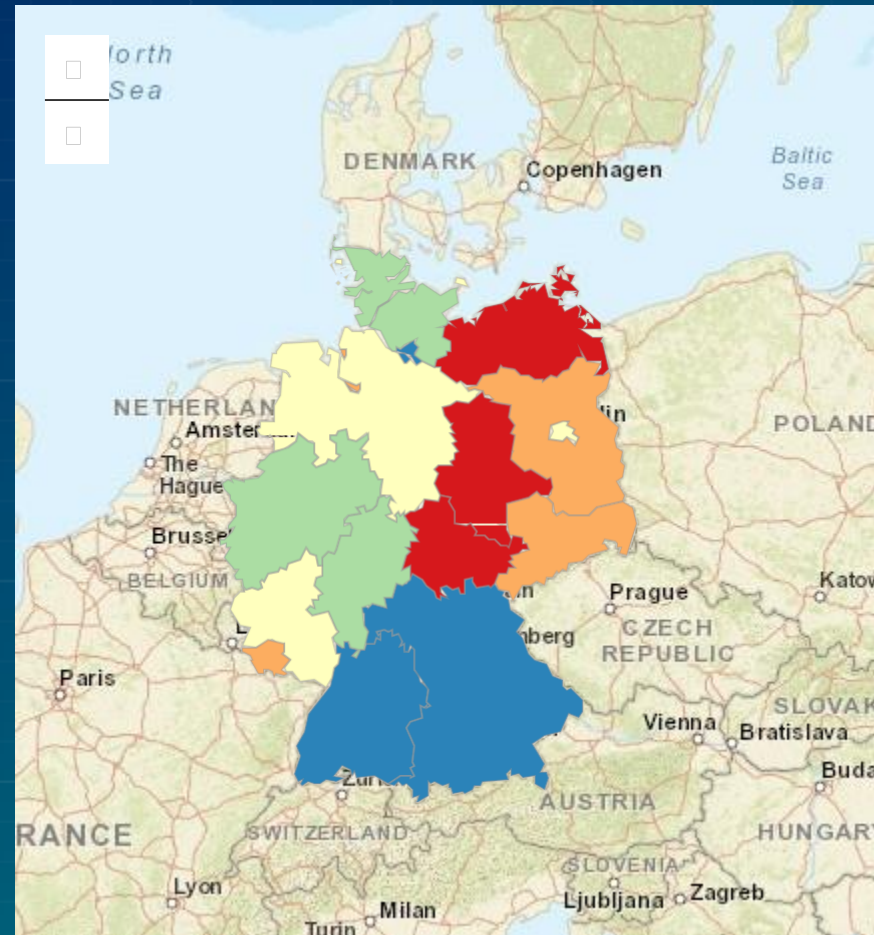
Added value of LiDAR & 3D Integrate Mesh to existing 3D.

3D Data on the Web

The background of the slide is an abstract composition. The upper two-thirds of the image are filled with a textured, wavy pattern in shades of orange and red, resembling crumpled paper or a topographical map. The lower third of the image features a dark blue, wavy border that separates the orange section from a bottom area containing a lighter blue grid pattern, which looks like a stylized city street map or a data visualization.

JavaScript API — 2D & 3D Viewing

```
var map = new Map({  
  basemap: "streets",  
  
  layers: [new FeatureLayer(  
    "...Germany/FeatureServer/0"  
  )]  
});  
  
viewLeft = new MapView({  
  container: "viewDivLeft",  
  
  map: map  
});  
  
viewRight = new SceneView({  
  container: "viewDivRight",  
  
  map: map  
});
```

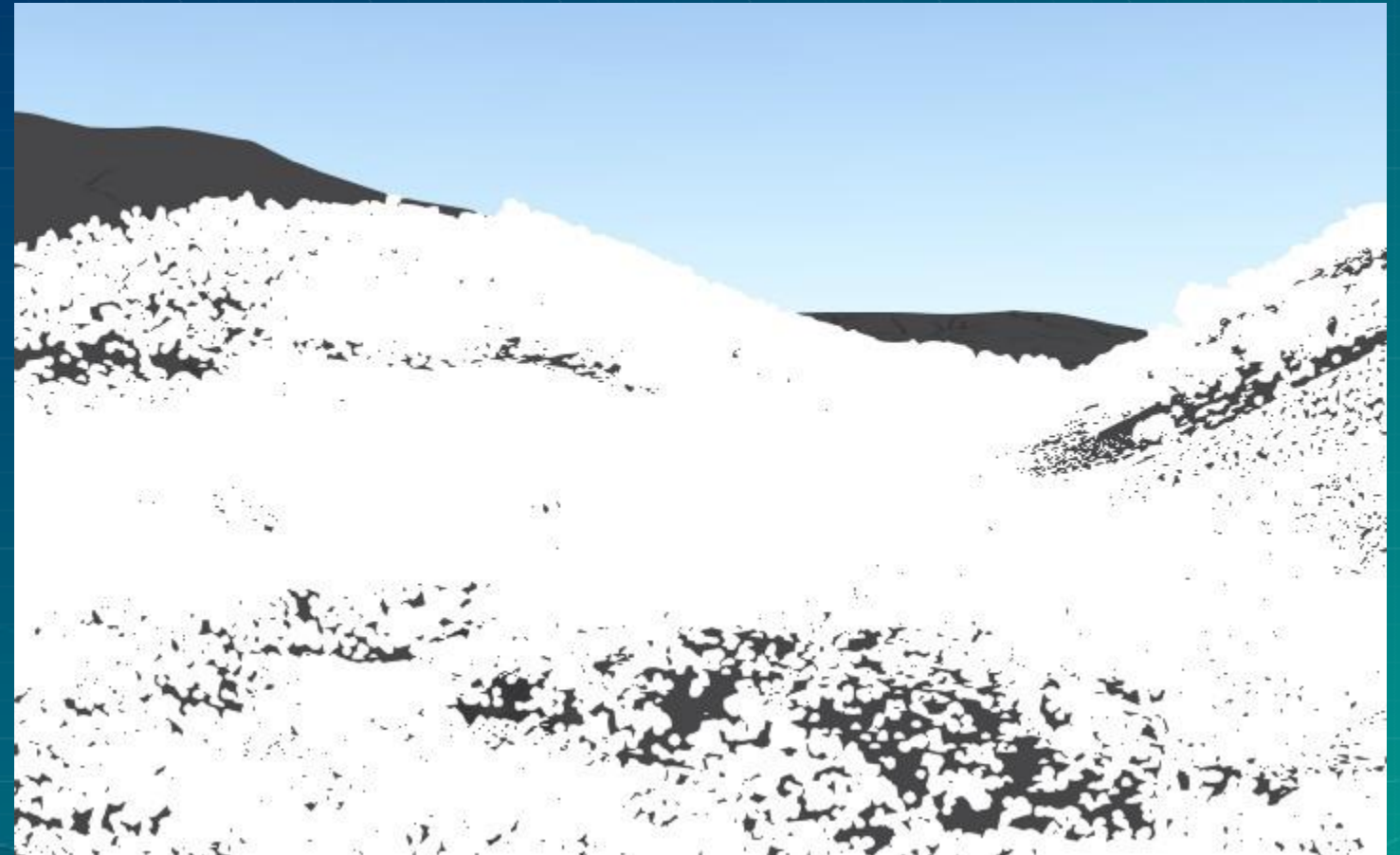


PointClouds —*Renderers*

- *RGBRenderer*
 - Use attribute value directly as color for point rendering
 - Only useful when data set contains RGB values in attributes
- *Stretch Renderer*
 - Define a color ramp, driven by a specific attribute
- *ClassBreaks Renderer*
 - Define value ranges that map to specific colors
- *UniqueValue Renderer*
 - Color by classification that is already present in a field

PointClouds — *RGBRenderer*

```
var layer = new PointCloudLayer({  
  url: "...sonoma8_lepcc/SceneServer",  
  renderer: new PointCloudRGBRenderer()  
});  
  
function changeRenderer() {  
  layer.renderer = new PointCloudRGBRenderer({  
    field: "RGB"  
  });  
}
```



PointClouds — *Stretch Renderer*

```
var layer = new PointCloudLayer({
  url: "...sonoma8_lepcc/SceneServer",
  renderer: new PointCloudRGBRenderer({ field: "RGB" })
});

function changeRenderer() {
  layer.renderer = new PointCloudStretchRenderer({
    field: "ELEVATION",
    stops: [{
      value: 0,
      color: "green"
    }, {
      value: 50,
      color: "yellow"
    }, {
      value: 100,
      color: "red"
    }]
  });
}
```



PointClouds — *ClassBreaksRenderer*

```
var layer = new PointCloudLayer({
  url: "...sonoma8_lepcc/SceneServer",
  renderer: new PointCloudRGBRenderer({ field: "RGB" })
});

function changeRenderer() {
  layer.renderer = new PointCloudClassBreaksRenderer({
    field: "INTENSITY",
    colorClassBreakInfos: [
      {
        minValue: 0,
        maxValue: 100,
        color: [100, 0, 0]
      }, {
        minValue: 100,
        maxValue: 200,
        color: [150, 0, 0]
      }, {
        minValue: 200,
        maxValue: 300,
        color: [200, 0, 0]
      }
    ]
  });
}
```



PointClouds — *UniqueValueRenderer*

```
var layer = new PointCloudLayer({
  url: "...sonoma8_lepcc/SceneServer",
  renderer: new PointCloudRGBRenderer({ field: "RGB" })
});

function changeRenderer() {
  layer.renderer = new PointCloudUniqueValueRenderer({
    field: "CLASS_CODE",
    colorUniqueValueInfos: [
      {
        values: [2],
        label: "Ground",
        color: [222, 184, 135]
      }, {
        values: [3, 4, 5],
        label: "Vegetation",
        color: [200, 232, 171]
      }, {
        values: [6],
        label: "Building",
        color: [158, 40, 17]
      }, {
        values: [7, 8, 9, 10, 11, 12],
        label: "Other",
        color: [50, 50, 50]
      }
    ]
  });
}
```

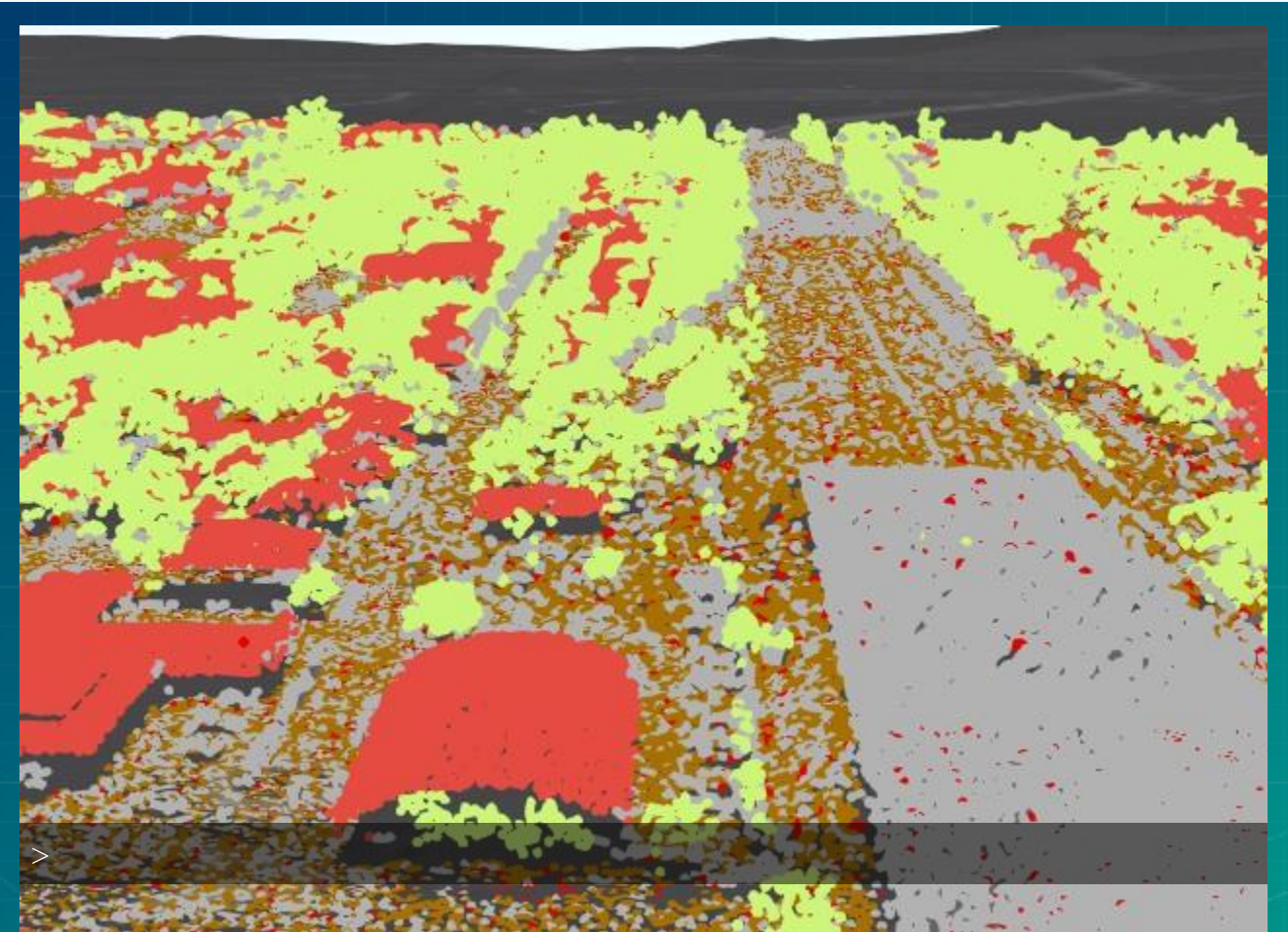


PointClouds — *Extended Properties*

- *colorModulation*
 - Alters brightness of points based on a data field
 - Displays scanned surfaces in a more realistic way
- *pointsPerInch*
 - Lets you configure the density of points on screen
 - Never exceeds a hard cap on the total number of points
- *pointSizeAlgorithm*
 - Two modes: splat and fixed-size
 - *Splat* automatically picks a size based on point density
 - *Fixed size* uses a constant size for all splats

PointClouds — *colorModulationProperty*

```
var layer = new PointCloudLayer({  
  url: "...sonoma8_lepcc/SceneServer",  
  renderer: new PointCloudUniqueValueRenderer(...)  
});  
  
var enabled = false; var  
colorModulation = {  
  field: "INTENSITY",  
  minValue: 35,  
  maxValue: 211  
};  
  
function changeRenderer() {  
  enabled = !enabled  
  
  layer.renderer = new PointCloudUniqueValueRenderer({  
    ...  
    colorModulation: enabled ? colorModulation : null  
  });  
}
```



PointClouds — *pointsPerInch* Property

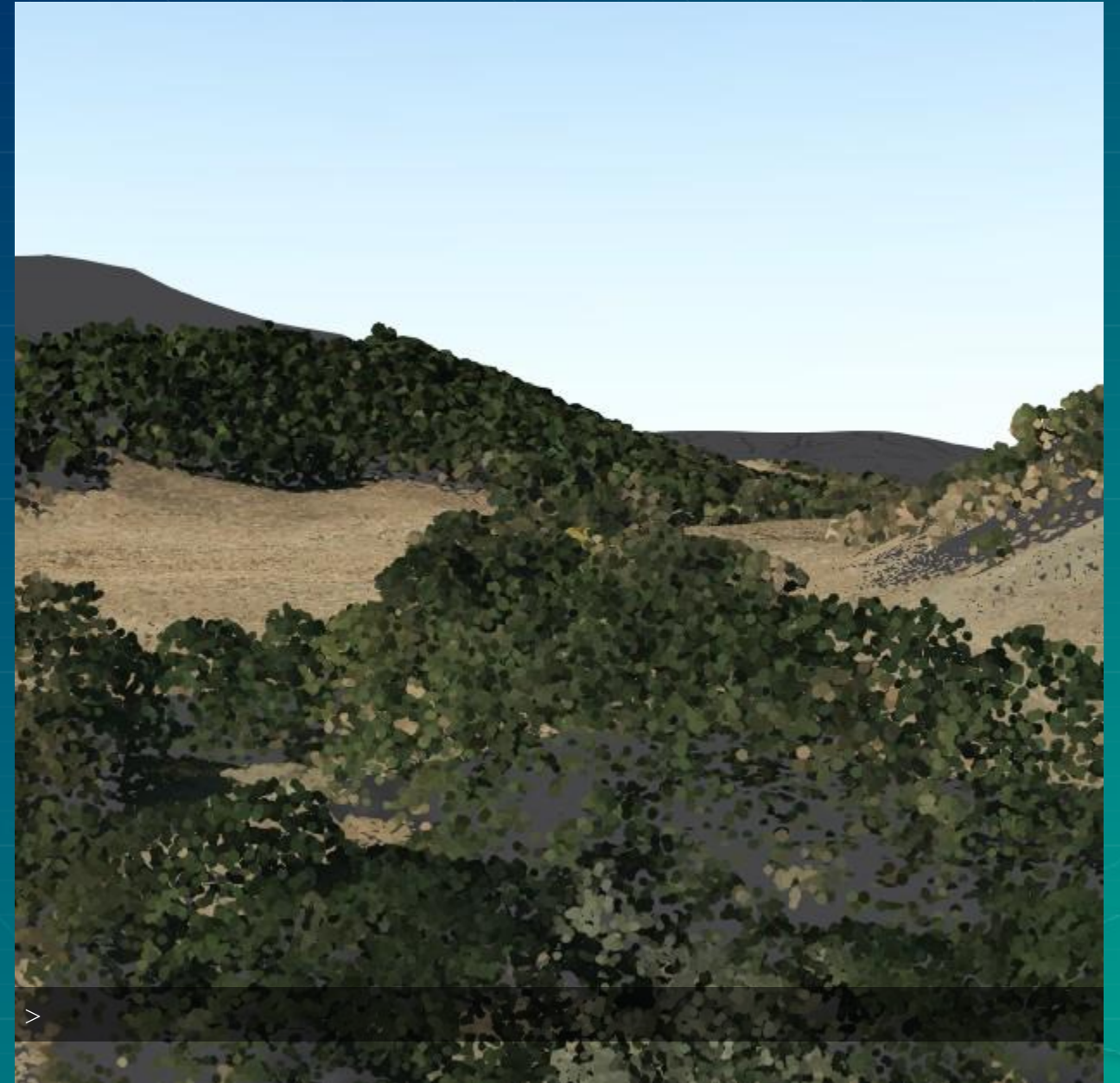
```
var layer = new PointCloudLayer({
  url: "...sonoma8_lepcc/SceneServer",
  renderer: new PointCloudRGBRenderer({ field: "RGB" })
});

var ppi = 40;

function changeRenderer() {
  switch (window.ppi) {
    case 10:
      ppi = 1;
      break;
    case 1:
      ppi = 40;
      break;
    default:
      ppi = 10;
      break
  }

  layer.renderer = new PointCloudRGBRenderer({
    field: "RGB",
    pointsPerInch: ppi
  });

  log("pointsPerInch:", ppi)
}
```



PointClouds — *pointSizeAlgorithm* Property

```
var layer = new PointCloudLayer({
  url: "...sonoma8_lepcc/SceneServer",
  renderer: new PointCloudRGBRenderer({ field: "RGB" })
});

var algorithm = "splat";

function changeRenderer() {
  if (algorithm === "splat") {
    layer.renderer = new PointCloudRGBRenderer({
      field: "RGB",
      pointSizeAlgorithm: { type: "splat" }
    });
  } else {
    layer.renderer = new PointCloudRGBRenderer({
      field: "RGB",
      pointSizeAlgorithm: { type: "fixed-size" }
    });
  }

  window.log("pointSizeAlgorithm:", algorithm);

  algorithm = algorithm === "splat" ? "fixed-size" : "splat"
}
```



Layers — *Common Properties*

- *elevationInfo*
 - Well known modes: *on-the-ground*, *relative-to-ground*, *absolute-height*
 - New mode: *relative-to-scene*
- *verticalOffset*
 - Allows offsetting all points in a layer by a given amount
- *callout*
 - Gives visual clues between features and map points

SceneLayer — *Relative To Scene Elevation*

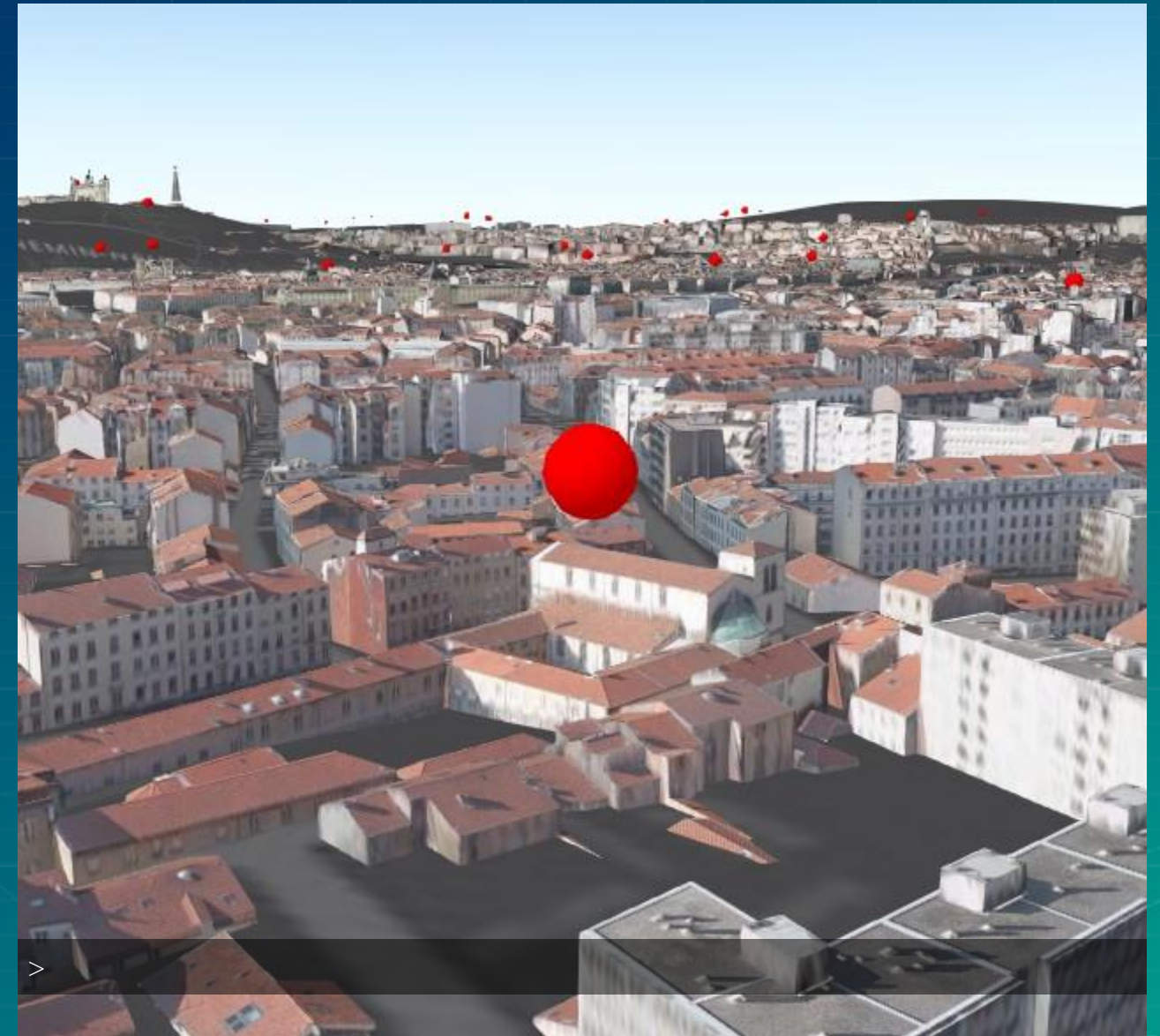
```
var sceneLayer = new SceneLayer({
  url: "...Batiments_Lyon_3D_2012/SceneServer",
  renderer: new SimpleRenderer(...)
});

var elevationMode = "relative-to-scene";

var featureLayer = new SceneLayer({
  url: "...LyonPointsOfInterest/FeatureServer",
  renderer: new UniqueValueRenderer(...),
  elevationInfo: {
    mode: elevationMode
  }
});

function changeLayer() {
  if (elevationMode === "relative-to-scene") {
    elevationMode = "relative-to-ground";
  }
  else {
    elevationMode = "relative-to-scene";
  }

  featureLayer.elevationInfo = { mode: elevationMode }
  window.log("elevationInfo.mode:", elevationMode)
}
```



SceneLayer — *Vertical Offset & Callouts*

```
var featureLayer = new SceneLayer({
  url: "...LyonPointsOfInterest/FeatureServer",
  renderer: new UniqueValueRenderer(...)
});

var offset = 20; function
changeLayer() {
  if (offset < 60) { offset += 20; }
  else { offset = 20; }

  featureLayer.renderer = new UniqueValueRenderer({
    uniqueValueInfos: [
      symbol: {
        symbolLayers: [
          new PointSymbol3D({
            verticalOffset: { screenLength: offset },
            callout: new LineCallout3D(...)
          })
        ]
      }
    ]
  });

  window.log("offset:", offset)
}
```



3D GIS Jumpstart

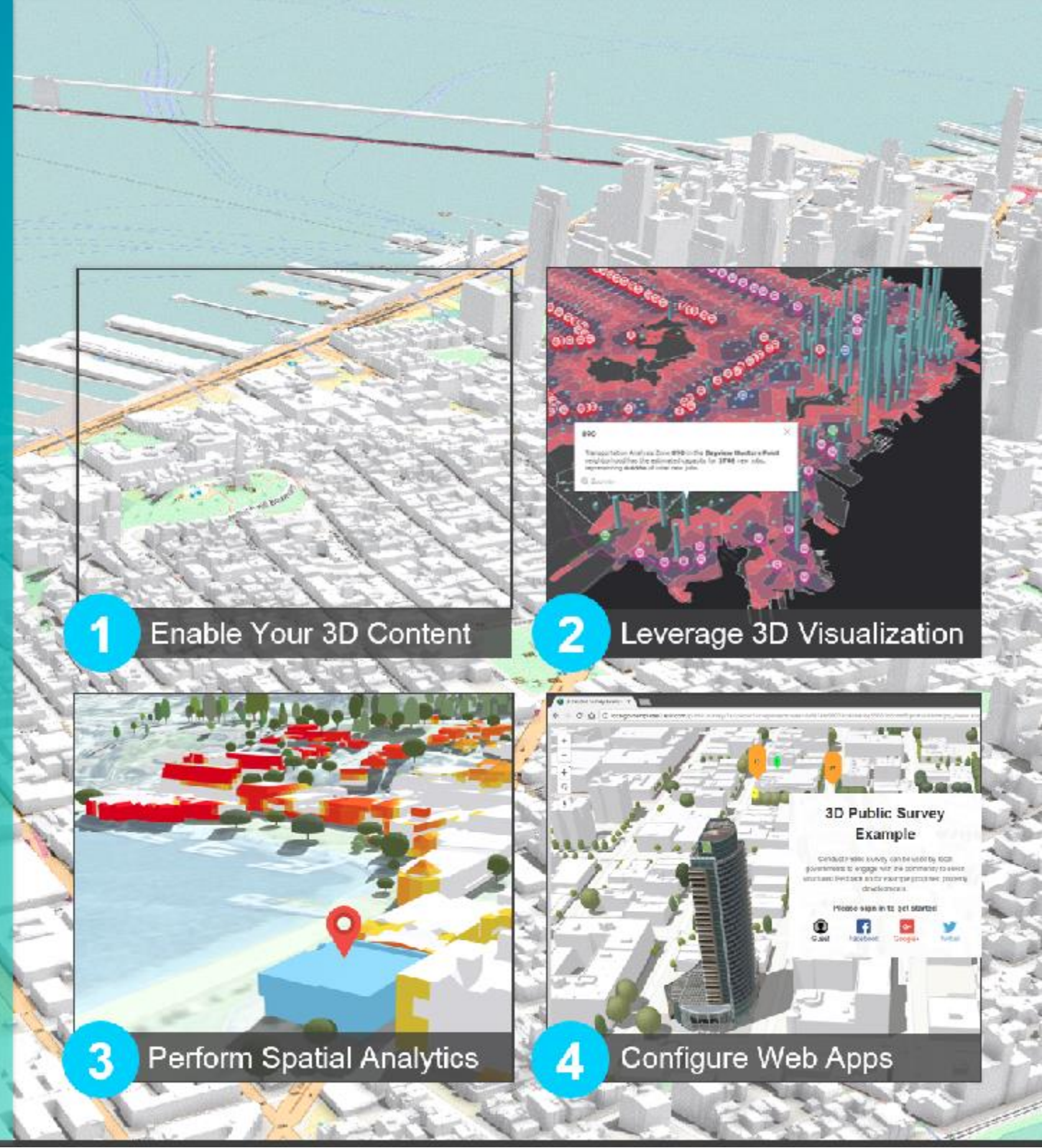
Organized as a phased set of workshop activities

Dive deep into working with 3D in ArcGIS

- Learn advanced 3D workflows and techniques
- Hands-on, one-on-one
- Your data in your environment
- Align with a current project for immediate ROI

Connect with an Expert: 3DConsulting@esri.com

Learn more about Esri's strategy and vision for Enterprise 3D GIS bit.ly/Enterprise_3D_GIS



1 Enable Your 3D Content



2 Leverage 3D Visualization



3 Perform Spatial Analytics



4 Configure Web Apps



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WHERE